

PROGRAMMABLE CONTROLLERS



MELSEC iQ-F FX5 User's Manual (MELSEC Communication Protocol)

SAFETY PRECAUTIONS

(Read these precautions before use.)

Before using this product, please read this manual and the relevant manuals introduced in this manual carefully and pay full attention to safety in order to handle the product correctly.

This manual classifies the safety precautions into two categories: [WARNING] and [CAUTION].

! WARNING

Indicates that incorrect handling may cause hazardous conditions, resulting in death or severe injury.

A CAUTION

Indicates that incorrect handling may cause hazardous conditions, resulting in medium or slight personal injury or physical damage.

Depending on the circumstances, procedures indicated by [(CAUTION] may also cause severe injury. It is important to follow all precautions for personal safety.

Store this manual in a safe place so that it can be read whenever necessary. Always forward it to the end user.

[DESIGN PRECAUTIONS]

MARNING

- Make sure to set up the following safety circuits outside the PLC to ensure safe system operation
 even during external power supply problems or PLC failure. Otherwise, malfunctions may cause
 serious accidents.
 - (1) Note that when the PLC CPU detects an error, such as a watchdog timer error, during self-diagnosis, all outputs are turned off. Also, when an error that cannot be detected by the PLC CPU occurs in an input/output control block, output control may be disabled. External circuits and mechanisms should be designed to ensure safe machine operation in such a case.
- When executing control (data change) to a running other station programmable controller by connecting the external device to the MC protocol compatible device, configure interlock circuits in the program of the other station programmable controller to ensure that the entire system operates safely at any time.
 - For other controls to a running other station programmable controller (such as program modification or operating status change), read relevant manuals carefully and ensure the safety before the operation. Especially, in the case of a control from an external device to a remote other station programmable controller, immediate action cannot be taken for a problem on the programmable controller due to a communication failure.
 - Determine the handling method as a system when communication failure occurs along with configuration of interlock circuit on other station PLC program, by considering external equipment and other station PLC.
- Do not write any data into the "system area" or "write protect area" of the buffer memory in the MC protocol compatible device or intelligent function module. Also, do not output (ON) any "use prohibited" signals among the signals which are output to the MC protocol compatible device and intelligent function device. Executing data writing to the "system area" or "write protect area", or outputting "use prohibited" signals may cause malfunction of the programmable controller alarm.

[STARTUP AND MAINTENANCE PRECAUTIONS]

MARNING

- Before modifying the program in operation, forcible output, running or stopping the PLC, read through this manual carefully, and ensure complete safety. An operation error may damage the machinery or cause accidents.
- Do not change the program in the PLC from two or more peripheral equipment devices at the same time. (i.e. from an engineering tool and a GOT)
 Doing so may cause destruction or malfunction of the PLC program.

[STARTUP AND MAINTENANCE PRECAUTIONS]

<u>^</u>CAUTION

 Read relevant manuals carefully and ensure the safety before performing online operations (operation status change) with peripheral devices connected to the running MC protocol compatible device or CPU modules of other stations. Improper operation may damage machines or cause accidents.

INTRODUCTION

This manual explains the specifications and settings related to the MC protocol of the MELSEC iQ-F Series. It should be read and understood before attempting to install or use the module. Always forward it to the end user.

Regarding use of this product

- This product has been manufactured as a general-purpose part for general industries, and has not been designed or manufactured to be incorporated in a device or system used in purposes related to human life.
- Before using the product for special purposes such as nuclear power, electric power, aerospace, medicine or passenger movement vehicles, consult Mitsubishi Electric.
- This product has been manufactured under strict quality control. However when installing the product where major accidents or losses could occur if the product fails, install appropriate backup or failsafe functions in the system.

Note

- If in doubt at any stage during the installation of the product, always consult a professional electrical engineer who is qualified and trained to the local and national standards. If in doubt about the operation or use, please consult the nearest Mitsubishi Electric representative.
- Since the examples indicated by this manual, technical bulletin, catalog, etc. are used as a reference, please use it after confirming the function and safety of the equipment and system. Mitsubishi Electric will accept no responsibility for actual use of the product based on these illustrative examples.
- · This manual content, specification etc. may be changed without a notice for improvement.
- The information in this manual has been carefully checked and is believed to be accurate; however, if you notice a doubtful point, an error, etc., please contact the nearest Mitsubishi Electric representative. When doing so, please provide the manual number given at the end of this manual.

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RELEVANT MANUALS

User's manuals for the applicable modules

| Manual name <manual number=""></manual> | Description |
|---|--|
| MELSEC iQ-F FX5 User's Manual (Startup) <jy997d58201></jy997d58201> | Performance specifications, procedures before operation, and troubleshooting of the CPU module. |
| MELSEC iQ-F FX5U User's Manual (Hardware) <jy997d55301></jy997d55301> | Describes the details of hardware of the FX5U CPU module, including input/output specifications, wiring, installation, and maintenance. |
| MELSEC iQ-F FX5UC User's Manual (Hardware) <jy997d61401></jy997d61401> | Describes the details of hardware of the FX5UC CPU module, including input/output specifications, wiring, installation, and maintenance. |
| MELSEC iQ-F FX5 User's Manual (Application) <jy997d55401></jy997d55401> | Describes basic knowledge required for program design, functions of the CPU module, devices/labels, and parameters. |
| MELSEC iQ-F FX5 Programming Manual (Program Design) <jy997d55701></jy997d55701> | Describes specifications of ladders, ST, FBD/LD, and other programs and labels. |
| MELSEC iQ-F FX5 Programming Manual (Instructions, Standard Functions/Function Blocks) <jy997d55801></jy997d55801> | Describes specifications of instructions and functions that can be used in programs. |
| MELSEC iQ-F FX5 User's Manual (Serial Communication) <jy997d55901></jy997d55901> | Describes N:N network, MELSEC Communication protocol, inverter communication, non-protocol communication, and predefined protocol support. |
| MELSEC iQ-F FX5 User's Manual (MELSEC Communication Protocol) <jy997d60801> (This manual)</jy997d60801> | Explains methods for the device that is communicating with the CPU module by MC protocol to read and write the data of the CPU module. |
| MELSEC iQ-F FX5 User's Manual (MODBUS Communication) <jy997d56101></jy997d56101> | Describes MODBUS serial communication. |
| MELSEC iQ-F FX5 User's Manual (Ethernet Communication) <jy997d56201></jy997d56201> | Describes the functions of the built-in Ethernet port communication function. |
| MELSEC iQ-F FX5 User's Manual (SLMP) <jy997d56001></jy997d56001> | Explains methods for the device that is communicating with the CPU module by SLMP to read and write the data of the CPU module. |
| MELSEC iQ-F FX5 User's Manual (Positioning Control) <jy997d56301></jy997d56301> | Describes the built-in positioning function. |
| MELSEC iQ-F FX5 User's Manual (Analog Control) <jy997d60501></jy997d60501> | Describes the analog function. |
| GX Works3 Operating Manual <sh-081215eng></sh-081215eng> | System configuration, parameter settings, and online operations of GX Works3. |

TERMS

Unless otherwise specified, this manual uses the following terms.

 $\bullet \; \square$ indicates a variable part to collectively call multiple models or versions.

(Example) FX5U-32MR/ES, FX5U-32MT/ES

⇒ FX5U-32M□/ES

• For details on the FX3 devices that can be connected with the FX5, refer to FX5 User's Manual (Hardware).

| Terms | Description |
|--|---|
| ■Devices | |
| FX5 | Generic term for FX5U and FX5UC PLCs |
| FX3 | Generic term for FX3S, FX3G, FX3GC, FX3U, and FX3UC PLCs |
| FX5 CPU module | Generic term for FX5U CPU module and FX5UC CPU module |
| FX5U CPU module | Generic term for FX5U-32MR/ES, FX5U-32MT/ES, FX5U-32MT/ESS, FX5U-64MR/ES, FX5U-64MT/ES, FX5U-64MT/ESS, FX5U-80MR/ES, FX5U-80MT/ESS, and FX5U-80MT/ESS |
| FX5UC CPU module | Generic term for FX5UC-32MT/D and FX5UC-32MT/DSS |
| Extension module | Generic term for FX5 extension modules and FX3 function modules |
| FX5 extension module | Generic term for I/O modules, FX5 extension power supply module, and FX5 intelligent function module |
| FX3 extension module | Generic term for FX3 extension power supply module and FX3 special function blocks |
| Extension module (extension cable type) | Input modules (extension cable type), Output modules (extension cable type), Bus conversion module (extension cable type), and Intelligent function modules |
| Extension module (extension connector type) | Input modules (extension connector type), Output modules (extension connector type), Input/output modules, Bus conversion module (extension connector type), and Connector conversion module (extension connector type) |
| I/O module | Generic term for input modules, output modules, Input/output modules, and powered input/output modules |
| Input module | Generic term for Input modules (extension cable type) and Input modules (extension connector type) |
| Input module (extension cable type) | Generic term for FX5-8EX/ES and FX5-16EX/ES |
| Input module (extension connector type) | Generic term for FX5-C32EX/D and FX5-C32EX/DS |
| Output module | Generic term for output modules (extension cable type) and output modules (extension connector type) |
| Output module (extension cable type) | Generic term for FX5-8EYR/ES, FX5-8EYT/ES, FX5-8EYT/ESS, FX5-16EYR/ES, FX5-16EYT/ES, and FX5-16EYT/ESS |
| Output module (extension connector type) | Generic term for FX5-C32EYT/D and FX5-C32EYT/DSS |
| Input/output modules | Generic term for FX5-C32ET/D and FX5-C32ET/DSS |
| Powered input/output module | Generic term for FX5-32ER/ES, FX5-32ET/ES, and FX5-32ET/ESS |
| Extension power supply module | Generic term for FX5 extension power supply module and FX3 extension power supply module |
| FX5 extension power supply module | Different name for FX5-1PSU-5V |
| FX3 extension power supply module | Different name for FX3U-1PSU-5V |
| Intelligent module | The abbreviation for intelligent function modules |
| Intelligent function module | Generic term for FX5 intelligent function modules and FX3 intelligent function modules |
| FX5 intelligent function module | Generic term for FX5 intelligent function modules |
| FX3 intelligent function module | Generic term for FX3 special function blocks |
| Simple motion module | Different name for FX5-40SSC-S |
| Expansion board | Generic term for board for FX5U CPU module |
| Communication board | Generic term for FX5-232-BD, FX5-485-BD, and FX5-422-BD-GOT |
| Expansion adapter | Generic term for adapter for FX5 CPU module |
| Communication adapter | Generic term for FX5-232ADP and FX5-485ADP |
| Analog adapter | Generic term for FX5-4AD-ADP and FX5-4DA-ADP |
| Bus conversion module | Generic term for Bus conversion module (extension cable type) and Bus conversion module (extension connector type) |
| Bus conversion module (extension cable type) | Different name for FX5-CNV-BUS |
| Bus conversion module (extension connector type) | Different name for FX5-CNV-BUSC |
| Battery | Different name for FX3U-32BL |
| Peripheral device | Generic term for engineering tools and GOTs |
| GOT | Generic term for Mitsubishi Graphic Operation Terminal GOT1000 and GOT2000 series |

| Terms | Description |
|---|--|
| ■Software packages | |
| Engineering tool | The product name of the software package for the MELSEC programmable controllers |
| GX Works3 | The product name of the software package, SWnDND-GXW3, for the MELSEC programmable controllers (The 'n' represents a version.) |
| ■Manuals | |
| User's manual | Generic term for separate manuals |
| User's manual (Startup) | Abbreviation of MELSEC iQ-F FX5 User's Manual (Startup) |
| FX5 User's manual (Hardware) | Generic term for MELSEC iQ-F FX5U User's Manual (Hardware) and MELSEC iQ-F FX5UC User's Manual (Hardware) |
| FX5U User's manual (Hardware) | Abbreviation of MELSEC iQ-F FX5U User's Manual (Hardware) |
| FX5UC User's manual (Hardware) | Abbreviation of MELSEC iQ-F FX5UC User's Manual (Hardware) |
| User's manual (Application) | Abbreviation of MELSEC iQ-F FX5 User's Manual (Application) |
| Programming manual (Program Design) | Abbreviation of MELSEC iQ-F FX5 Programming Manual (Program Design) |
| Programming manual (Instructions, Standard Functions/Function Blocks) | Abbreviation of MELSEC iQ-F FX5 Programming Manual (Instructions, Standard Functions/Function Blocks) |
| Communication manual | Generic term for MELSEC iQ-F FX5 User's Manual (Serial Communication), MELSEC iQ-F FX5 User's Manual (MELSEC Communication Protocol), MELSEC iQ-F FX5 User's Manual (MODBUS Communication), MELSEC iQ-F FX5 User's Manual (Ethernet Communication), and MELSEC iQ-F FX5 User's Manual (SLMP) |
| Serial communication manual | Abbreviation of MELSEC iQ-F FX5 User's Manual (Serial Communication) |
| MC protocol manual | Abbreviation of MELSEC iQ-F FX5 User's Manual (MELSEC Communication Protocol) |
| MODBUS communication manual | Abbreviation of MELSEC iQ-F FX5 User's Manual (MODBUS Communication) |
| Ethernet communication manual | Abbreviation of MELSEC iQ-F FX5 User's Manual (Ethernet Communication) |
| SLMP manual | Abbreviation of MELSEC iQ-F FX5 User's Manual (SLMP) |
| Positioning manual | Abbreviation of MELSEC iQ-F FX5 User's Manual (Positioning Control) |
| Analog manual | Abbreviation of MELSEC iQ-F FX5 User's Manual (Analog Control) |
| ■Communication-related | |
| Built-in RS-485 port | Built-in RS-485 port of the CPU module. |
| Serial port | Generic term for the four ports consisting of the FX5 Series built-in RS-485 port (CH1), communication board (CH2), communication adapter 1 (CH3), and communication adapter 2 (CH4). |
| MC protocol | The abbreviation of the MELSEC communication protocol. A protocol for accessing MC protocol-compatible devices and PLCs that are connected to MC protocol-compatible devices from external devices. |
| MC protocol-compatible device | Generic term for devices that can receive MC protocol messages. |
| SLMP | The abbreviation for Seamless Message Protocol. A protocol for accessing SLMP-compatible devices and PLCs that are connected to SLMP-compatible devices from external devices. |
| SLMP-compatible device | Generic term for devices that can receive SLMP messages. |
| External device | Generic term for devices of communication target (such as personal computer, HMI) |
| Connected station (host station) | Connected station (host station) indicates a station directly connected to external device. |
| Other station | Other station indicates a station connected to the connected station (host station) on the network. |
| Relay station | A station that includes two or more network modules. Transient transmission is performed through this station to stations on other networks. |
| Module access device | A generic term for the module access device of the MELSEC iQ-R series/MELSEC iQ-F series and intelligent function module device of the MELSEC-Q/L series |
| Buffer memory | Memory areas of Intelligent function modules for storing setting values and monitor values. |

1 OUTLINE

This manual describes the method for reading or writing data in a CPU module with the data communication function of the external device using MC protocol (serial communication).

When transferring data using MC protocol, always refer to F Page 10 MC PROTOCOL DATA COMMUNICATION.

1.1 Outline of MC Protocol

MC protocol (MELSEC communication protocol) is a protocol used for access from a CPU module or an external device (such as a personal computer or an HMI) to an MC protocol compatible device.

MC protocol communications are available among devices that can transfer messages by MC protocol.

In case of a serial port of FX5, communication is possible by 3C/4C frame compatible with QnA of the MC protocol.

Device data in a CPU module can be written or read from a personal computer or an HMI by using MC protocol.

Writing and reading the device allows operation monitoring, data analyzing, and production managing of a CPU module by a personal computer or an HMI.

The following shows the flow for starting MC protocol communication.

1. Connect cables and external devices.

Configure the connection for the MC protocol communication.

For details, refer to the following manual.

MELSEC iQ-F FX5 User's Manual (Serial Communication)

2. Set parameters.

Set parameters with engineering tool.

3. Write the set parameters to the CPU module.

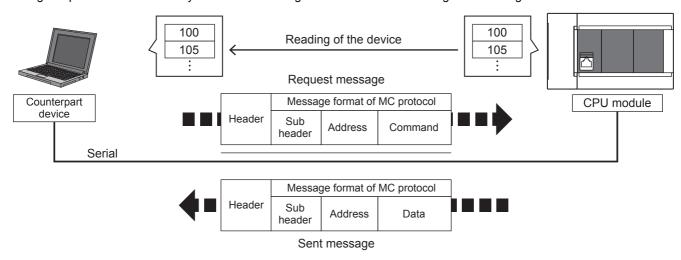
Write set parameters to a CPU module. Validate the parameters by turning off to on or resetting the system.

1.2 Features of MC Protocol

System monitoring from an external device (such as personal computer, HMI)

An external device can send a request message in MC protocol message format to a CPU module to enable device read, allowing system monitoring.

Using MC protocol allows not only device data reading but also device data writing and resetting an CPU module.



2 MC PROTOCOL DATA COMMUNICATION

This chapter describes the MC protocol data communication by which the external device reads or writes data to a CPU module.

2.1 Type and Application of the Data Communication Frame

This section describes the type and application of the frame (data communication message) by which the external device accesses a CPU module with MC protocol.

When the external device accesses a CPU module using serial communication, the data communication is executed by sending or receiving a request message (access request) and response message of the following frame.

| Target communication method | Applicable communication frames | Features and purposes | Communication data code | Section of control procedure |
|-----------------------------|---------------------------------|---|---------------------------|------------------------------|
| serial communication | 4C frame | Accessible from external devices with the maximum access range. | ASCII code or binary code | Page 14 MESSAGE FORMAT |
| | 3C frame | These message formats are simplified compared to the 4C frame. | binary code | Page 14 MESSAGE FORMAT |



FX5 CPU module supports 3E frame (Ethernet communication) of MC protocol.

The message format of 3E frame of MC protocol is the same as that of the 3E frame of SLMP. For details on 3E frame of SLMP, refer to the following manual.

- QMELSEC iQ-F FX5 User's Manual (SLMP)
- MELSEC iQ-F FX5 User's Manual (Ethernet Communication)

2.2 Concept of Control Procedure of MC Protocol

This section describes the concept of the procedure (control procedure) when the external device accesses a CPU module with MC protocol.

Sending a request message

Data communication using MC protocol communication is executed in half-duplex communication.

To access the CPU module, send the next request message after receiving a response message for the preceding request message from the CPU module.

(Until the receiving of the response message is completed, the next request message cannot be sent.)



When a response message of completion for a request message cannot be received

■When a response message of completion with an error is received

Take corrective actions depending on the error code in the response message.

■When a response message or all messages cannot be received

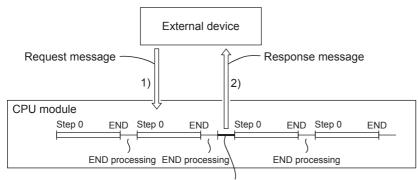
Resend a request message after the monitoring time of the response monitoring timer elapses.

Change the set value of the monitoring time as needed.

2.3 Access Timing of the CPU Module Side

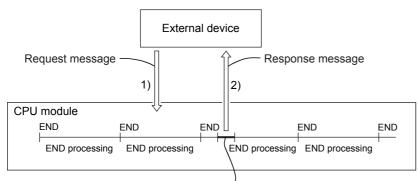
The following shows the access timing of the CPU module side when the CPU module is accessed from the external device using the serial communication port.

• RUN



Processing for a command from the external device

STOP



Processing for a command from the external device

- 1. To send a read request or a write request to the CPU module side from the external device, a request message is sent.
- 2. The CPU module reads or writes the data according to the description requested from the external device when the END instruction of the CPU module is executed and sends a response message including the processing result to the external device of the request source.



- Access between the external device and CPU module is processed at each END processing when the CPU module is running for a command request. (The scan time becomes longer by the processing time of the command request.)
- When accesses are requested simultaneously to the CPU module from multiple external device, the processing requested from the external device may be on hold until several END processings take place depending on the request timing.

2.4 Transfer Time

Link time

■Data transfer



■Data transfer time

R: Number of read data points, W: Number of written data points, T: Time to send or receive one character, V: Interval time, S: Max Scan Time of PLC,

D: Message waiting time

(1) 3C Frame

Time to read continuous word devices (data registers etc.) in one station (ms)

$$=(43^{*1} + 4 \times R^{*2}) \times T \text{ (ms)} + V + S \text{ (SD524)} \times 3 + D$$

Time to write continuous word devices (data registers etc.) in one station (ms)

$$=(42^{*1} + 4 \times W^{*2}) \times T \text{ (ms)} + V + S \text{ (SD524)} \times 3 + D$$

*1 This is the number of characters when format1 is used and the sum check is not provided at the time of execution of batch read/write command.

When format4 is used, add "4" to this value.

Further, when the sum check is provided, add "4" to this value also.

Further, when specifying an extension, add "+7" to this value also.

- *2 The number of points is counted in 1-word units.
- (2) 4C Frame: In case of ASCII code (When format1 to format4 are used)

Time to read continuous word devices (data registers etc.) in one station (ms)

$$=(49^{*3} + 4 \times R^{*4}) \times T \text{ (ms)} + V + S \text{ (SD524)} \times 3 + D$$

Time to write continuous word devices (data registers etc.) in one station (ms)

$$=(48^{*3} + 4 \times W^{*4}) \times T \text{ (ms)} + V + S \text{ (SD524)} \times 3 + D$$

*3 This is the number of characters when format1 is used and the sum check is not provided at the time of execution of batch read/write command.

When format4 is used, add "4" to this value.

Further, when the sum check is provided, add "4" to this value also.

Further, when specifying an extension, add "+7" to this value also.

- *4 The number of points is counted in 1-word units.
- (3) 4C Frame: In case of binary code (When format5 is used)

Time to read continuous word devices (data registers etc.) in one station (ms)

$$=(42^{*5} + 4 \times R^{*6}) \times T \text{ (ms)} + V + S \text{ (SD524)} \times 3 + D$$

Time to write continuous word devices (data registers etc.) in one station (ms)

$$=(40^{*5} + 4 \times W^{*6}) \times T \text{ (ms)} + V + S \text{ (SD524)} \times 3 + D$$

*5 This is the number of characters when format5 is used and the sum check is not provided at the time of execution of batch read/write command.

Further, when the sum check is provided, add "4" to this value also.

Further, when specifying an extension, add "+7" to this value also.

When "10H" exists in the data area, since DLE "10H" is added just before "10H", add "+ "10H numeral".

*6 The number of points is counted in 1-word units.

■Time to send or receive one character

The table below shows the time required to send or receive one character when the start bit is 1-bit, the data length is 7-bit, the parity is 1-bit, and the stop bit is 1-bit (total 10-bits).

| Transmission speed (baud rate) (bps) | Time to send or receive 1 character (ms) |
|--------------------------------------|--|
| 300 | 33.34 |
| 600 | 16.67 |
| 1200 | 8.34 |
| 2400 | 4.17 |
| 4800 | 2.08 |
| 9600 | 1.04 |
| 19200 | 0.52 |
| 38400 | 0.26 |
| 57600 | 0.17 |
| 115200 | 0.08 |

The tables below show the data transfer times depending on the number of continuously read or written word devices at transmission speeds of 9600 bps and 19200 bps when the message waiting time is 0 ms^{*1}, the maximum scan time is 20 ms, and the interval time is 100 ms.

• When the transmission speed is 9600 bps (Unit: Second)

| Number of data points | Number of stations | | | | |
|-----------------------|--|-----|-----|--|--|
| | Station No. 1 Station No. 8 Station No. 16 | | | | |
| 10 points | 0.3 | 1.9 | 3.7 | | |
| 32 points | 0.4 | 2.6 | 5.2 | | |
| 64 points | 0.5 | 3.7 | 7.3 | | |

• When the transmission speed is 19200 bps (Unit: Second)

| Number of data points | Number of stations | Number of stations | | | | |
|-----------------------|--------------------|--|-----|--|--|--|
| | Station No. 1 | Station No. 1 Station No. 8 Station No. 16 | | | | |
| 10 points | 0.2 | 1.6 | 3.2 | | | |
| 32 points | 0.3 | 2.0 | 3.9 | | | |
| 64 points | 0.4 | 2.5 | 5.0 | | | |

When the types of read or written devices increase, "Data transfer time shown in above table \times Number of device types" is required.

When the number of read or written points exceeds "64", the transfer time increases.

Accordingly, for achieving efficient data transfer, it is recommended to decrease the number of types of transferred devices and use as many continuous device numbers as possible.

*1 When RS-485 one-pair wiring using FX-485PC-IF is adopted, the message waiting time (for every exchange) must be 70 to 150ms. When RS-485 two-pair wiring or RS-232C is adopted, the message waiting time becomes 0ms.

3 MESSAGE FORMAT

This chapter describes the message data format, the data specification method, and limitations etc. when performing MC protocol data communication using the 3C/4C frame to the serial communication port.

3.1 Types and Purposes of Messages

The messages of MC protocol can be classified as shown in the following table depending on the supported device and its intended purpose.

Formats and codes

There are five formats for the message that can be used for serial communication module.

| Format | Code of communication data | Remarks | Reference | Corresponding of FX5 | GX Works3 setting |
|----------|----------------------------|---|------------------|----------------------|----------------------------|
| Format 1 | ASCII code | _ | Page 15 Format 1 | 0 | Message Pattern: Pattern 1 |
| Format 2 | ASCII code | Format with block number appended | _ | × | _ |
| Format 3 | ASCII code | Format enclosed with STX and ETX | _ | × | _ |
| Format 4 | ASCII code | Format with CR and LF appended at the end | Page 16 Format 4 | 0 | Message Pattern: Pattern 4 |
| Format 5 | Binary code | Can be used by 4C frame. | Page 17 Format 5 | 0 | Message Pattern: Pattern 5 |

^{○:} Applicable, ×: Not applicable

Set the format with the module parameter of GX Works3.



Communication using binary code shorten the communication time since the amount of communication data is reduced by approximately half as compared to the one using ASCII code.

Frame

This section explains the types and purposes of the frames (data communication messages) used by the external device to access the supported devices using MC protocol.

The frames for MC protocol (serial communication) are as follows:

| Frame | Features and purposes | Compatible message format | Format | Corresponding of FX5 |
|----------|--|--|----------------|---------------------------------------|
| 4C frame | Accessible from external devices with the maximum access range. | Dedicated protocols for MELSEC-QnA series serial communication modules (QnA extension frame). | Formats 1 to 5 | Corresponding to formats 1, 4, and 5. |
| 3C frame | These message formats are simplified compared to the 4C frame. Data communication software for MELSEC-QnA | Dedicated protocols for MELSEC-QnA series serial communication modules (QnA frame). | | Corresponding to formats 1 and 4. |
| 2C frame | series programmable controllers can be used. | Dedicated protocols for MELSEC-QnA series serial communication modules (QnA simplified frame). | | × |
| 1C frame | These frames have the same message structures as when accessing the CPU module using an FX3 or MELSEC-A series computer link module. Data communication software for FX3 or MELSEC-A series programmable controllers can be used. | Dedicated protocols for MELSEC-A series computer link modules | | × |

^{○:} Applicable, ×: Not applicable

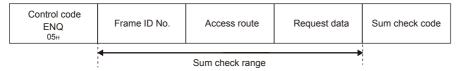
3.2 Message Formats of Each Protocol

This section explains the message format and setting data per each format.

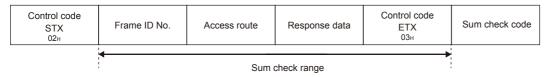
Format 1

Message format

■Request message



■Response message (Normal completion: Response data)



■Response message (Normal completion: No response data)

| Control code ACK 06H | Frame ID No. | Access route |
|----------------------------|--------------|--------------|
|----------------------------|--------------|--------------|

■Response message (Abnormal completion)

| Control code NAK | Frame ID No. | Access route | Error code |
|---------------------|--------------|--------------|------------|
| 15н | | | |

Setting data

| Item | Description | Reference |
|---|--|--|
| Control code (ENQ, STX, ACK, NAK, ETX) | A code is defined for control. | Page 18 Control code |
| Frame ID No. | Specify the frame to be used. | Page 20 Frame ID No. |
| Access route | Specify the access route. | Page 23 Accessible Ranges and Settable Data for Each Frame |
| Request data | Set the command that indicates the request content. Refer to "Request data" rows of each command. | Page 29 COMMANDS |
| Response data | Store the read data for the command. Refer to "Response data" rows of each command. | |
| Sum check code | The value of the lower one byte (8 bits) of the additional result regarding the data in the sum check target range as a binary data. | Page 20 Sum check code |
| Error code | Error code indicates the content of occurred error. | Page 22 Error code |

Format 4

Message format

■Request message



■Response message (Normal completion: Response data)

| Control code STX 02H | Frame ID No. | Access route | Response data | Control code ETX 03H | Sum check code | Contr CR _{0DH} | ol code LF 0A _H |
|----------------------------|--------------|--------------|---------------|----------------------------|----------------|-------------------------------|----------------------------------|
| | | | | | | | |
| | | | | | | | |

■Response message (Normal completion: No response data)

| Control code | | _ | Contro | ol code |
|--------------|--------------|--------------|-----------|-----------|
| АСК 06н | Frame ID No. | Access route | CR 0DH | LF 0Aн |

■Response message (Abnormal completion)

| Control code | | | | Contro | ol code |
|--------------|--------------|--------------|------------|--------|---------|
| NAK | Frame ID No. | Access route | Error code | CR | LF |
| 15н | | | | 0DH | 0Ан |

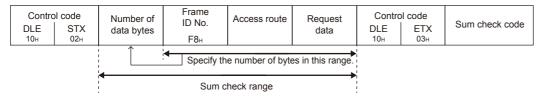
Setting data

| Item | Description | Reference |
|---|--|---|
| Control code (ENQ, STX, ACK, NAK, ETX, CR, LF) | A code is defined for control. | Page 18 Control code |
| Frame ID No. | Specify the frame to be used. | Page 20 Frame ID No. |
| Access route | Specify the access route. | Page 23 Accessible Ranges and Settable Data for Each Frame |
| Request data | Set the command that indicates the request content. Refer to "Request data" rows of each command. | Page 29 COMMANDS |
| Response data | Store the read data for the command. Refer to "Response data" rows of each command. | |
| Sum check code | The value of the lower one byte (8 bits) of the additional result regarding the data in the sum check target range as a binary data. | Page 20 Sum check code |
| Error code | Error code indicates the content of occurred error. | Page 22 Error code |

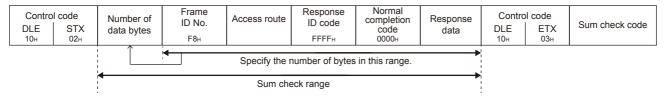
Format 5

Message format

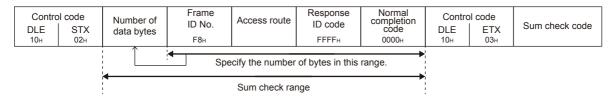
■Request message



■Response message (Normal completion: Response data)



■Response message (Normal completion: No response data)



■Response message (Abnormal completion)

| Contro DLE 10 _H | STX 02H | Number of data bytes | Frame ID No. F8 _H | Access route | Response ID code FFFF _H | Error codes | Contro DLE 10 _H | Ol code ETX 03H | Sum check code |
|--|------------|----------------------|------------------------------------|--------------|--|----------------|----------------------------------|-----------------------|----------------|
| Specify the number of bytes in this range. | | | | 1 | | | | | |
| | | Sum check range | | | 1 | | | | |

Setting data

| Item | Description | Reference |
|---------------------------------|--|---|
| Control code (DLE, STX, ETX) | A code is defined for control. | Page 18 Control code |
| Number of data bytes | The number of bytes from the frame ID No. to control code (DLE, ETX). | Page 19 Number of data bytes |
| Frame ID No. | Specify the frame to be used. | Page 20 Frame ID No. |
| Access route | Specify the access route. | Page 23 Accessible Ranges and Settable Data for Each Frame |
| Request data | Set the command that indicates the request content. Refer to "Request data" rows of each command. | Page 29 COMMANDS |
| Response data | Store the read data for the command. Refer to "Response data" rows of each command. | |
| Sum check code | Im check code The value of the lower one byte (8 bits) of the additional result regarding the data in the sum check target range as a binary data. Page 20 S | |
| Response ID code | This indicates a response message. The 2-byte numerical value, 'FFFH' is stored. | _ |
| Normal completion code | This indicates the processing is completed normally. The 2-byte value, '000H' is stored. | _ |
| Error code | Error code indicates the content of occurred error. | Page 22 Error code |

3.3 Details of Setting Data (Format)

This section explains how to specify the common data items and their content in each message.

Control code

Control code is a data that has special meaning (such as head data of a message) for transmission control.

Control code used in a message (format 1 to format 4) in ASCII code

The control code used for a message in ASCII code (format 1 to format 4) is shown in the following table.

| Symbol name | Description | Code (hexadecimal) |
|-------------|----------------------|--------------------|
| STX | Start of Text | 02H |
| ETX | End of Text | 03H |
| EOT | End of Transmission | 04H |
| ENQ | Enquiry | 05H |
| ACK | Acknowledge | 06H |
| LF | Line Feed | 0AH |
| CL | Clear | 0CH |
| CR | Carriage Return | 0DH |
| NAK | Negative Acknowledge | 15H |

■EOT(04H), CL(0CH)

EOT and CL are codes for initializing the transmission sequence for data communications in ASCII code using the MC protocol and for placing CPU module into wait state to receive commands from an external device.

The transmission sequence is initialized with the command (command code: 1615) when binary code (format 5) is used. When performing the following at an external device, send the EOT/CL to the CPU module depending on the format used.

- Canceling a read/write request by command previously sent. (If a write request is issued, the write request cannot be canceled when the data has already written to the CPU module.)
- · Placing CPU module into the wait state to receive commands before commands are sent.
- Placing CPU module into the state where it has been started up when data communication cannot be performed normally. The message structure when sending EOT, CL is shown below.

Only the following data is sent. The station No. and PC No. are not required.

| Format | ЕОТ | CL | | |
|----------|--------------------------|-------------------------|--|--|
| Format 1 | EOT 04H | CL 0CH | | |
| Format 4 | EOT CR LF 04H 0DH 0AH | CL CR LF 0CH 0DH 0AH | | |

When CPU module receives EOT or CL, it proceeds as follows.

- Terminates any read/write processing performed upon request from the external device. In this case, CPU module does not send a response message to the command previously received.
- CPU module initializes the transmission sequence using the MC protocol and placing CPU module into wait state to receive commands from an external device.
- CPU module does not send a response message to the EOT or CL reception. (It does not send anything to external devices.)

Control code used in a message (format 5) in binary code

The control code used for a message in binary code (format 5) is shown in the table below.

| Symbol name | Description | Code (hexadecimal) |
|-------------|------------------|--------------------|
| STX | Start of Text | 02H |
| ETX | End of Text | 03H |
| DLE | Data Link Escape | 10H |

■Additional code (10H)

The additional code is added to distinguish the data when the control code (10H) is the same as the setting data in frame 5. When '10H' is included in the data from "Number of data bytes" and "Request data" in the request message, the additional code '10H' is added in front of the data.

When '10H' is included in the data from "Number of data bytes" and "Response data" in the response message, the additional code '10H' is added.

('10H' is transmitted as '10H' + '10H'.)



Calculate the following value except for the additional code.

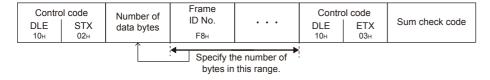
- · Number of data bytes (setting item of format 5)
- · Sum check code

Number of data bytes

A number of data bytes indicates the total number of bytes from the frame ID No. to control code.

Range

Calculate the data in the range from frame ID No. before DLE (10H) except for the additional code. (Page 19 Additional code (10H))



Setting method

Set the data in binary code (format 5) at data communication.

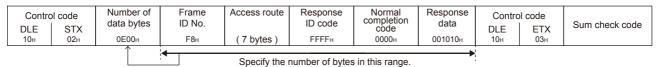
Send 2-byte numerical value from the lower byte (L: bits 0 to 7).

Ex.

Response message (Normal completion: Response data)

- Frame ID No.: 1 byteAccess route: 7 byte
- Response ID code, normal completion code: 4 bytes
- Response data: 2 bytes + additional code (10H) 1 byte

Number of data bytes = 1 + 7 + 4 + 2 = 14 (0EH)



Block number

Block number is an arbitrary number defined by an external device and used for data defragmentation.

Block number converts data to 2-digit (hexadecimal) ASCII code within the range of '00H' to 'FFH' and sends them from the upper digits.

CPU module only checks if the block number is specified within the correct range. It does not check whether the block numbers are sent in order.

Frame ID No.

Specify the frame to be used.

| Туре | Setting value |
|----------|---------------|
| 4C frame | F8 |
| 3C frame | F9 |

Setting method

■Data communication in ASCII code

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

■Data communication in binary code

Send 1-byte numerical value.



For 4C frame (F8)

| ASCII code | Binary code |
|--------------|-------------|
| F 8 46H, 38H | F8H |

Sum check code

Set the sum check code when performing sum check.

For sum check code, set the value to be calculated from the data with the range of sum check for error detection.

Sum check

Sum check is a function for detecting error when data changes while data transmission.

Set the sum check existence by Engineering tool.

■When sum check code is set to "Exist"

Attach a sum check code to the request message.

CPU module checks the sum check code. The sum check code is added to the response message.

■When sum check code is set to "None"

The sum check code is not required for the request message.

CPU module does not check the sum check code. The sum check code is not added to the response message.

Sum check range

The sum check range of each message format is as follows:

| Format | Message structure | Reference |
|----------|---|------------------|
| Format 1 | Control code Sum check code | Page 15 Format 1 |
| | Sum check range | |
| Format 4 | Control code Sum check code CR LF 0DH 0AH | Page 16 Format 4 |
| | Sum check range | |
| Format 5 | Control code Control code DLE ETX 10H 03H Sum check code | Page 17 Format 5 |
| | Sum check range | |

Calculation of a sum check code

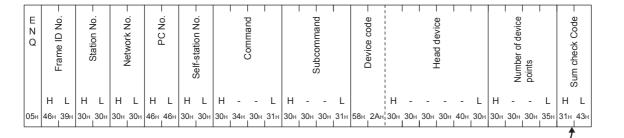
For sum check code, set the numerical values of the lower 1 byte (8 bits) of the added result (sum) as binary data within the sum check range.

Calculate sum check code except for the additional code. (Page 19 Additional code (10H))



In the following case of 3C frame format 1, the sum check code will be '1C'.

Formula: 46H + 39H + 30H + 30H + 30H + 30H + 30H + 46H + 46H + 30H + 3

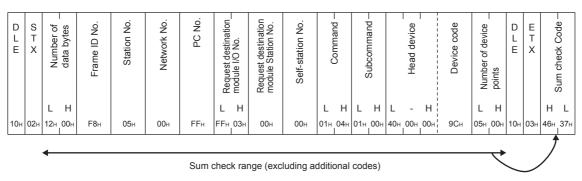


Sum check range

In the following case of 4C frame format 5, the sum check code will be 'F7'.

Formula: 12H + 00H + F8H + 05H + 00H + FFH + FFH + 03H + 00H + 00H + 01H + 04H + 01H + 00H + 40H + 00H + 00H + 9CH + 05H + 00H = 3F7H

Sum check code: 'F7' (ASCII code 46H, 37H)



Setting method

■Data communication in ASCII code

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

■Data communication in binary code

The same as data communication in ASCII code, use the numerical value converted to 2 digit ASCII code (hexadecimal). Send 2-byte numerical value from the lower byte (L: bits 8 to 15).



Sum check code: 'F7' (ASCII code 46H, 37H)

ASCII code, binary code



Error code

Error code indicates the content of occurred error.

If more than one error occurs at the same time, the error code detected first is returned.

For the content of error code and its corrective action, refer to the following manual.

MELSEC iQ-F FX5 User's Manual (Serial Communication)

MELSEC iQ-F FX5 User's Manual (Application)

Setting method

■Data communication in ASCII code

Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

■Data communication in binary code

Send 2-byte numerical value from the lower byte (L: bits 0 to 7).



When error code 7143H is returned

| ASCII code | Binary code |
|--|-------------|
| 7 1 4 3 37 _H , 31 _H , 34 _H , 33 _H | 43H , 71H |

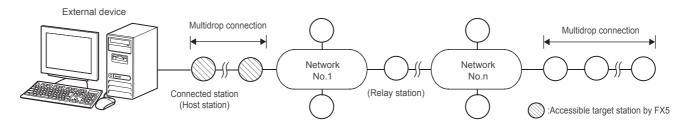
3.4 Accessible Ranges and Settable Data for Each Frame

The accessible range of each frame and the data items to set an access route are as shown below.

4C frame

Accessible range of 4C frame

The following ranges can be accessed.



Message format (Setting example for accessing connected station (host station))

■Data communication in ASCII code (Format 1, Format 4)

| Network No. | | | | uest de odule I/ | stinatior O No. | | | estinatio ation No | | | | | | | |
|----------------|--------|-------|-----|---------------------|--------------------|-----|-----|-----------------------|-----|-----|-----|-----|----------|-----------|--|
| | Statio | n No. | | | PC | No. | | | | | | | Self-sta | ition No. | |
| | 0 | 0 | 0 | 0 | F | F | 0 | 3 | F | F | 0 | 0 | 0 | 0 | |
| | 30н | 30н | 30н | 30н | 46н | 46н | 30н | 33н | 46н | 46н | 30н | 30н | 30н | 30н | |

■Data communication in binary code (Format 5)

| N | letworl No. | k F | | st destination ule I/O No. | | Request destination module station No. | | |
|---|----------------|-----|-----|-------------------------------|-----|--|-----|--|
| | 12. | | | k | | | | |
| (| Station | i ¦ | PC | | ¦ s | elf-stat | ion | |
| | No. | - 1 | No. | | - 1 | No. | | |
| | | | | | | | | |
| | 00н | 00н | FFн | FFн 03н | 00н | 00н | | |

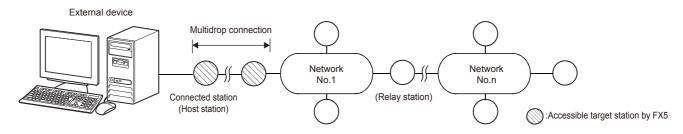
Data to be set

| Item | Description | Reference | |
|--|---|--|--|
| Station No. | Specify the station to be connected from an external device. | Page 25 Station No. | |
| Network No. | Specify the access target network No. | Page 26 Network No., PC No. | |
| PC No. | Specify the network No. number of the access target. | | |
| Request destination module I/O No. | Specify the start I/O number of a connection source module (relay station) of multidrop connection via network. | Page 27 Request destination module I/O No., request destination module | |
| Request destination module station No. | Specify the station No. of an access target module of multidrop connection via network. | station No. | |
| Self-station No. | At the time of m:n multidrop connection, specify the station No. of a request source external device. | Page 28 Self-station No. | |

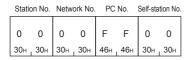
3C frame

Accessible range of 3C frame

The following ranges can be accessed.



Message format (Setting example for accessing connected station (host station))



Data to be set

| Item | Description | Reference | | |
|------------------|---|--------------------------|--|--|
| Station No. | Specify the station to be connected from an external device. | Page 25 Station No. | | |
| Network No. | Specify the access target network No. Page 26 Network No., PC No. | | | |
| PC No. | Specify the network station No. of the access target. | | | |
| Self-station No. | At m:n multidrop connection, specify the station No. of a request source external device. | Page 28 Self-station No. | | |

3.5 Details of Setting Data (Frame)

This section explains the content and specification method of the data items to set the access route.

| Item | 4C frame | 3C frame | Reference |
|--|----------|----------|---|
| Station No. | 0 | 0 | Page 25 Station No. |
| Network No. | 0 | 0 | Page 26 Network No., PC No. |
| PC No. | | | |
| Request destination module I/O No. | 0 | _ | Page 27 Request destination module I/O No., request destination |
| Request destination module station No. | | | module station No. |
| Self-station No. | 0 | 0 | Page 28 Self-station No. |

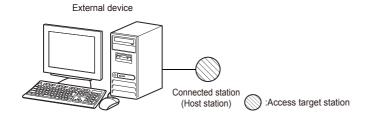
○: Necessary, —: Unnecessary

Station No.

Specify the station accessed from an external device.

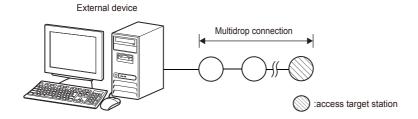
Accessing connected station (host station)

Specify '0' when accessing connected station (host station).



Accessing multidrop connection station

For the multidrop connection, specify the station No. to be accessed from 0 to 31 (00H to 1FH).



Setting method

The station No. is specified by the following parameter items of engineering tool, and writes the "module parameter" in the CPU module.

• GX Works3: "Station Number Settings" in "Module Parameter"

■Data communication in ASCII code

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

■Data communication in binary code

Send 1-byte numerical value.



When the station No. setting for CPU module to be accessed is '5'

| ASCII code | Binary code |
|----------------|-------------|
| 0 5 30н 35н | 05н |

Network No., PC No.

Specify the network No. and station No. that are set with the parameters for the access target network module. Specify a fixed value when accessing the connection station.

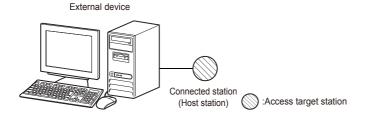


Specify the network No. with the value shown below.

Specifying improper value may result in no response returned.

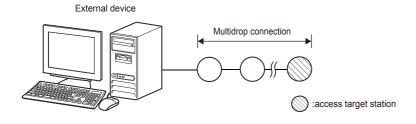
Accessing connected station (host station)

Specify '0' for the network No., and 'FF' for the PC No.



Accessing multidrop connection station

Specify '0' for the network No., and 'FF' for the PC No.



Setting method

■Data communication in ASCII code

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

■Data communication in binary code

Send 1-byte numerical value.



Accessing connected station (host station) or multidrop connection station

| ASCII code | Binary code |
|-----------------------|-----------------------|
| Network PC No. No. | Network PC No. No. |
| 0 0 F F | |
| 30н 30н 46н 46н | 00H FFH |

Request destination module I/O No., request destination module station No.

The following fixed value is specified in FX5 CPU module.

| Request destination module I/O No. | Request destination module station No. |
|------------------------------------|--|
| 03FFH | 00H |

Setting method

■Data communication in ASCII code

For the request destination module I/O No., convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

For the request destination module station No., convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

■Data communication in binary code

For the request destination module I/O No., the 2-byte value is sent from the lower byte (L: bit 0 to 7).

For the request destination module station No., the 1-byte value is sent.

Ex.

Accessing connected station (host station)

| ASCII code | Binary code |
|--|--|
| Request destination module I/O No. Request destination module station No. 0 3 F F 0 0 30H 33H 46H 46H 30H 30H | Request destination module I/O No. Request destination module station No. |

Self-station No.

The following fixed value is specified in FX5 CPU module.

| Self-station No. | |
|------------------|--|
| 00H | |

Setting method

■Data communication in ASCII code

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

■Data communication in binary code

Send 1-byte numerical value.



When 00H is specified

| ASCII code | Binary code |
|--|-------------|
| 0 0 30 _{H 1} 30 _H | 00н |

4 COMMANDS

This chapter explains commands of MC protocol.

4.1 List of Commands and Functions

The functions of a message is defined by each command. The message format for request data and response data varies with commands. Depending on the type of frame to be used, the specific value is assigned to a command. The value of command is specified at the head of a request data.

| Request message | | | | | |
|-----------------|---|--------------|-------------------|----------|---|
| Control code | | Access route | Request data ··· | | |
| | | | | | |
| | | | Command | | |
| Response messag | е | | | <u> </u> |] |
| Control code | | Access route | Response data ··· | | |

The explanation of each command in Part 3, the message format of request data and response data are explained. For the message formats other than request data and response data, refer to the following sections.

Page 14 MESSAGE FORMAT

Command List

3C/4C frame

| Name | Comm ands | Sub- comm and | Contents of processing | Number of points processed in one-time update |
|-------------------------|--------------|---|--|---|
| Batch read | 0401H | 0001H | Reads data in 1-point units from bit devices or word devices. | ASCII: 3584 points BIN: 3584 points |
| | | 0000H | Reads data in 16-point units from bit devices. Reads data in 1-word unit from word devices. | 960 words (15360 points |
| | | 0081H | Reads data in 1-bit unit from buffer memory of intelligent unit. Reads data in 1-bit unit from a device indirectly specified in the index register. | ASCII: 3584 points BIN: 3584 points |
| | | H0800 | Reads data in 1-word unit from buffer memory of intelligent unit. Reads data in 1-word unit from a device indirectly specified in the index register. | 960 words (15360 points |
| | | 0083H | Reads data in 1-bit unit from buffer memory of intelligent unit. Reads data in 1-bit unit from a device indirectly specified in the index register. | ASCII: 3584 points BIN: 3584 points |
| | | 0082H | Reads data in 1-word unit from buffer memory of intelligent unit. Reads data in 1-word unit from a device indirectly specified in the index register. | 960 words (15360 points |
| Batch write | 1401H | 0001H | Writes data in 1-bit units to bit devices. | ASCII: 3584 points BIN: 3584 points |
| | | 0000H | Writes data in 16-bit units to bit devices. Writes data in 1-word units to bit devices. | 960 words (15360 points |
| 0081H 0080H 0083H | 0081H | Writes data in 1-bit unit to MC protocol compatible devices or buffer memory of intelligent unit. Indirectly specifies bit devices, word devices and buffer memory in the index register. | ASCII: 3584 points BIN: 3584 points | |
| | 0080H | Writes data in 1-word (16-bits) unit to MC protocol compatible devices or buffer memory of intelligent unit. | 960 words (15360 points | |
| | 0083H | Writes data in 1-bit unit to MC protocol compatible devices or buffer memory of intelligent unit. | ASCII: 3584 points BIN: 3584 points | |
| | 0082H | Writes data in 1-word (16-bits) unit to MC protocol compatible devices or buffer memory of intelligent unit. | 960 words (15360 points | |
| | 0000H | Reads a word device in 1-word unit or 2-word unit by randomly specifying the device number. | 192 points | |
| | 0080H | Reads data in 1-word (16-bit) unit from MC protocol compatible devices or buffer memory of intelligent unit. | 192 points | |
| | | 0082H | Reads data in 1-word (16-bit) unit from MC protocol compatible devices or buffer memory of intelligent unit. | 192 points |
| Random write | 1402H | 0001H | Writes data in 1-bit unit to a bit device by randomly specifying the device number. | 188 points |
| | | 0000H | Writes data in 16-bit unit to a bit device by randomly specifying the device number. Writes data in 1-word unit or 2-word unit to a word device by randomly specifying the device number. | (Number of word access points)×12+(number of double word access points)×14≤1920 |
| | | 0081H | Writes data in 1-bit unit to MC protocol compatible devices or buffer memory of intelligent unit. Indirectly specifies a buffer memory in the index register. | 188 points |
| | 0080H | Writes data in 1-word (16-bits) or 2-word unit to MC protocol compatible devices or buffer memory of intelligent unit. | (Number of word access points)×12+(number of double word access points)×14≤1920*1 | |
| | 0083H | Writes data in 1-bit unit to MC protocol compatible devices or buffer memory of intelligent unit. | 188 points | |
| | | 0082H | Writes data in 1-word (16-bits) unit or 2-word unit to MC protocol compatible devices or buffer memory of intelligent unit. | (Number of word access points)×12+(number of double word access points)×14≤1920*1 |

| Name | Comm ands | Sub- comm and | Contents of processing | Number of points processed in one-time update |
|------------------------------------|--------------|---------------------|--|---|
| Batch read multiple blocks | 0406H | 0000Н | Assumes an n point part of a bit device or word device as 1-block and reads data by randomly specifying the multiple blocks. (When specifying bit devices, 16-bit is intended in 1-point.) | 960 points |
| | | 0080H | Assumes an n point part of a MC protocol compatible devices or buffer memory of intelligent unit as 1-block and reads data by randomly specifying the multiple blocks. (When specifying bit devices, 16-bit is intended in 1-point.) | 960 points |
| | | 0082H | Assumes an n point part of a MC protocol compatible devices or buffer memory of intelligent unit as 1-block and reads data by randomly specifying the multiple blocks. | 960 points |
| Batch write multiple blocks | 1406H | 0000H | Assumes an n point part of a bit device or word device as 1-block and writes data by randomly specifying the multiple blocks. (When specifying bit devices, 16-bit is intended in 1-point.) | 770 points |
| | | 0080H | Assumes an n point part of a MC protocol compatible devices or buffer memory of intelligent unit as 1-block and writes data by randomly specifying multiple blocks. (When specifying bit devices, 16-bit is intended in 1-point.) | 770 points*1 |
| | | 0082H | Assumes an n point part of a MC protocol compatible devices or buffer memory of intelligent unit as 1-block and writes data by randomly specifying multiple blocks. | 770 points*1 |
| Remote RUN | 1001H | 0000H | Requests remote RUN to a device. | _ |
| Remote STOP | 1002H | 0000H | Requests remote STOP to a device. | _ |
| Remote PAUSE | 1003H | 0000H | Requests remote PAUSE to a device. | _ |
| Remote latch clear | 1005H | 0000H | Requests remote latch clear when a device is in STOP mode. | _ |
| Remote RESET | 1006H | 0000H | Requests remote reset to cancel error stop mode of a device. | _ |
| Read CPU model name | 0101H | 0000H | Reads a processor module name code (processor type) of a device. | _ |
| Loopback test | 0619H | 0000H | Checks if normal communication is possible. | _ |
| LED OFF, error code initialization | 1617H | 0000H | Clears all errors in batches and turns OFF LED. | _ |

^{*1} With device extension specification, the number of points that can be set become fewer. When using the device extension specification, calculate doubling the number of access points.

4.2 Device Access

This section explains the control procedure specification method and shows a specification example when the device memory is read and written.

Data to be Specified in Commands

This section explains the contents and specification methods for data items which are set in each command related to device access.

Subcommand

Subcommands are data for specifying the unit for reading and writing, device type to be specified, and the data reading condition.

The following table shows the details of setting items.

| Setting item | | Description |
|---|---|--|
| Data size specification Word units | | The target data is read or written in word units. Select "0" even when the reading data or writing data does not exist in arguments of the command. |
| | Bit units | The target data is read or written in bit units. |
| Device specification format 2 digit code/6 digit number specification | | Data or items related to the address specifications are expressed in the following sizes, which are the same as the existing setting. • Device code: 1 byte in binary • Device number: 3 bytes in binary |
| | 4 digit code/8 digit number specification | Data or items related to the address specifications are extended to the following size. • Device code: 2 byte in binary • Device number: 4 bytes in binary |
| Device memory Not specified extension specification | | Set this when specifying devices of a CPU module. * Set this when not using the device memory extension specification. |
| | Specified | Set this for the buffer memory specification of the intelligent function module. This setting corresponds to the buffer memory indirect specification with index register. |

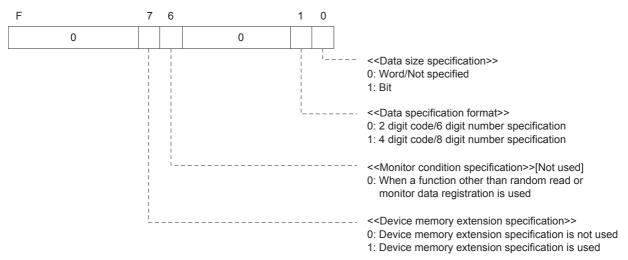
When communicating data in ASCII code

The value 0000H(0), or the following value, is converted to a 4 digit (hexadecimal) ASCII code and sequentially transmitted beginning from the most significant digit ("0").

When communicating data in binary code

The value 0000H, or the following 2-byte value, is used for transmission.

The following figure shows the specification contents of the subcommand.



4 In the following cases, the subcommand is 0000H or 0001H.

- When neither monitor condition nor device memory extension is specified.
- When using a command that cannot select monitor condition specification and device memory extension specification.

Devices

Specify the device to be accessed by device code and device number.

- · The data order differs between ASCII code and binary code.
- The data size to set up changes with setting of the device specification format of subcommand.

| Device specification format of subcommand | ASCII code | Binary code |
|---|--|--|
| 2 digit code/6 digit number specification | Device code Device number (2 digits) (6 digits) | Device Device number code (3 bytes) (1 byte) |
| 4 digit code/8 digit number specification | Device code Device number (4 digits) (8 digits) | Device number Device code (4 bytes) (2 bytes) |



When accessing any of the following devices, use the device extension specification (subcommand: 008 L).

· Module access device

For the message format for device extension specification, refer to the following section.

Page 85 Device Memory Extension Specification

Device codes

Specify the device name to be accessed.

Specify the device within the range of the access target module.

For the values of each device code, refer to the following section.

Page 35 Device code list

■Data communication using ASCII code

Convert the numerical value to 2-digit or 4-digit ASCII code (hexadecimal), and send it from the upper digits.

- For 2 digit code/6 digit number specification: 2-digit ASCII code
- For 4 digit code/8 digit number specification: 4-digit ASCII code

The '*' in a device code can also be specified with a space (code: 20H).

■Data communication using binary code

Send the 1-byte or 2-byte numerical value from the lower byte (L: bits 0 to 7).

- For 2 digit code/6 digit number specification: 1 byte
- For 4 digit code/8 digit number specification: 2 bytes



For input (X)

| Device specification format of subcommand | ASCII code | Binary code |
|---|--|-------------|
| 2 digit code/6 digit number specification | X * 58H 2AH | 9Сн |
| 4 digit code/8 digit number specification | X * * * 58H ₁ 2AH ₁ 2AH | 9CH 100H |

Device number

Specify the number of the device to be accessed.

Specify the device number within the range of the access target module.

■Data communication using ASCII code

Convert the numerical value to 6-digit or 8-digit ASCII code, and sent it from the upper digits.

Specify the device number in decimal or hexadecimal, depending on the device type. (Page 35 Device code list)

- For 2 digit code/6 digit number specification: 6-digit ASCII code
- For 4 digit code/8 digit number specification: 8-digit ASCII code (10 digits at device extension specification)

The '0' in the upper digits can also be specified with a space (code: 20H).

■Data communication using binary code

Send the 3-byte or 4-byte numerical value in order from the lower byte (L: bit 0 to 7).

For a device of which device number is in decimal, convert it to hexadecimal and specify.

- For 2 digit code/6 digit number specification: 3 bytes^{*1}
- For 4 digit code/8 digit number specification: 4 bytes^{*1}
- *1 The additional code may be added. (Page 19 Additional code (10H))



For link relay (B) 1234 (a device of which device number is in hexadecimal)

| Device specification format of subcommand | ASCII code | Binary code |
|---|---|-----------------------|
| 2 digit code/6 digit number specification | 0 0 1 2 3 4 30H, 30H, 31H, 32H, 33H, 34H | 34н 12н 00н |
| 4 digit code/8 digit number specification | 0 0 0 0 1 2 3 4 30н, 30н, 30н, 30н, 31н, 32н, 33н, 34н | 34н , 12н , 00н , 00н |

For internal relay (M) 1234 (a device of which device number is in decimal)

For binary code, convert the device number to hexadecimal. '1234' (decimal) → '4D2' (hexadecimal)

| Device specification format of subcommand | ASCII code | Binary code |
|---|---|-----------------------|
| 2 digit code/6 digit number specification | 0 0 1 2 3 4 30н , 30н , 31н , 32н , 33н , 34н | D2н 104н 100н |
| 4 digit code/8 digit number specification | 0 0 0 0 1 2 3 4 30н, 30н, 30н, 30н, 31н, 32н, 33н, 34н | D2H , 04H , 00H , 00H |

For internal relay (M) 16 (with additional code)

For CPU module binary code, specify '10H' as '10H + 10H'. (Fig. Page 19 Additional code (10H))

| Device specification format of subcommand | Binary code |
|---|---------------------|
| 2 digit code/6 digit number specification | DLE 10H 10H 00H |
| 4 digit code/8 digit number specification | DLE 10H 10H 00H 00H |

Device code list

The table below shows devices and device number range that can handled in commands used in communication by MC protocol.

Specify devices and device number range that are there in the targeted unit for performing data reading, writing etc. In 3C/4C frame, in the following "Device Code", specify a device of the access point.

| Division Device | | | Type Device Code*1 (Device specification format: Long) | | Device No. | | FX5 device available*2 | |
|-----------------|-------------------------|------------------|--|------------|-------------|---|------------------------|---|
| | | | | ASCII code | Binary code | | | |
| Internal user | Input | | Bit | X* (X***) | 9CH (9C00H) | Specify within the | Octal | 0 |
| devices | Output | | 1 | Y* (Y***) | 9DH (9D00H) | range of device numbers that the unit | Octal | 0 |
| | Internal relay | | | M* (M***) | 90H (9000H) | at the access point | Decimal | 0 |
| | Latch relay Annunciator | | | L* (L***) | 92H (9200H) | bears. | Decimal | 0 |
| | | | | F* (F***) | 93H (9300H) | | Decimal | 0 |
| | Edge relay | | | V* (V***) | 94H (9400H) | | Decimal | _ |
| | Link relay | | | B* (B***) | A0H (A000H) | | Hexadecimal | 0 |
| | Step relay | | | S* (S***) | 98H (9800H) | | Decimal | 0 |
| | Data register | Data register | | D* (D***) | A8H (A800H) | | Decimal | 0 |
| | Link register | | Bit | W* (W***) | B4H (B400H) | | Hexadecimal | 0 |
| | Timer | Contact | | TS (TS**) | C1H (C100H) | | Decimal | 0 |
| | | Coil | | TC (TC**) | C0H (C000H) | | | 0 |
| | Long Timer | Present value | Word | TN (TN**) | C2H (C200H) | 0H) 0H) 0H) 0H) 0H) 0OH) 0OH) 0OH) 0OH) | | 0 |
| | | Contact | Bit | — (LTS*) | 51H (5100H) | | Decimal | _ |
| | | Coil | | — (LTC*) | 50H (5000H) | | | _ |
| | | Present value | Double word | — (LTN*) | 52H (5200H) | | | _ |
| | Retentive timer | Contact | Bit | SS (STS*) | C7H (C700H) | | Decimal | 0 |
| | | Coil | | SC (STC*) | C6H (C600H) | | | 0 |
| | | Present value | Word | SN (STN*) | C8H (C800H) | | | 0 |
| | Long Retentive Timer | Contact | Bit | — (LSTS) | 59H (5900H) | | Decimal | _ |
| | | Coil | | — (LSTC) | 58H (5800H) | | | _ |
| | | Present value | Double word | — (LSTN) | 5AH (5A00H) | | | _ |
| | Counter | Contact | Bit | CS (CS**) | C4H (C400H) | | Decimal | 0 |
| | | Coil | | CC (CC**) | C3H (C300H) | | | 0 |
| | | Present value | Word | CN (CN**) | C5H (C500H) | | | 0 |
| | Long counter | Contact | Bit | — (LCS*) | 55H (5500H) | | Decimal | 0 |
| | | Coil | | — (LCC*) | 54H (5400H) | | | 0 |
| | | Present value | Double word | — (LCN*) | 56H (5600H) | | | 0 |
| | Link special rela | у | Bit | SB (SB**) | A1H (A100H) | 1 | Hexadecimal | 0 |
| | Link special regi | ster | Word | SW (SW**) | B5H (B500H) | 1 | Hexadecimal | 0 |
| System | Special relay | | Bit | SM (SM**) | 91H (9100H) | Specify within the | Decimal | 0 |
| device | Special Register | Special Register | | SD (SD**) | A9H (A900H) | range of device numbers that the unit at the access point bears. | Decimal | 0 |
| | Command input | | Bit | _ | _ | _ | Hexadecimal | _ |
| | Command outpu | t | 1 | _ | _ | 1 | Hexadecimal | _ |
| | Function register | ٢ | Word | _ | _ | 1 | Decimal | _ |

| Division | Device | | | 1 ification) | Device No. | | FX5 device available*2 |
|----------------------|---|--------------|----------------|---------------------|-----------------|-------------|------------------------|
| | | | ASCII code | Binary code | | | |
| Index register | | 16 bit | Z* (Z***) | CCH (CC00H) | range of device | Decimal | 0 |
| | | 32 bit | LZ (LZ**) | 62H (6200H) | | Decimal | 0 |
| File register | | Word | R* (R***) | AFH (AF00H) | _ | Decimal | 0 |
| | | | ZR (ZR**) | B0H (B000H) | | Decimal | _ |
| Unit access device*3 | Link register Word Link special register | W* (W***) | B4H (B400H) | Hexadecimal | | _ | |
| | | | SW (SW**) | B5H (B500H) | | Hexadecimal | _ |
| | Module access device | | G* (G***) | ABH (AB00H) | | Decimal | 0 |

^{*1 [}ASCII code]

When a device code is less than the specified number of characters, add "*" (ASCII code: 2AH), or <space> (ASCII code: 20H) at the end of the device code.

[Binary code]

When a device code is less than the specified size, add "00H" at the end of the device code.

- *2 O: FX5 device
 - -: No FX5 device

Number of device points

Specify the number of device points to be read or written.

Setting method

■Data communication using ASCII code

Convert the numerical value to 4-digit ASCII code (hexadecimal), and send it from the upper digits.

Use capitalized code for alphabetical letter.

■Data communication using binary code

Send the 2-byte numerical value*1 in order from the lower byte (L: bit 0 to 7).

*1 The additional code may be added. (Page 19 Additional code (10H))



For 5 points and 20 points

| Number of device points | ASCII code | Binary code |
|-------------------------|----------------------------------|-------------|
| 5 points | 0 0 0 5 30н 30н 30н 35н | 05н , 00н |
| 20 points | 0 0 1 4 30H, 30H, 31H, 34H | 14н , 00н |

^{*3} It is necessary to make "Device memory extension specification" of the sub-command to ON (1).

Access points

Specify the number of device points to be accessed in word unit, double word unit, or bit unit.

It specifies within the number of points processed which can be performed by the one communication shown in the table (F Page 30) of the command list.

Setting method

■Data communication using ASCII code

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

Use capitalized code for alphabetical letter.

■Data communication using binary code

Send the 1-byte^{*1} numerical value (hexadecimal).

*1 The additional code may be added. (Page 19 Additional code (10H))



For 5 points and 20 points

| Number of device points | ASCII code | Binary code |
|-------------------------|--|-------------|
| 5 points | 0 5 30H ₁ 35H | 05н |
| 20 points | 1 4 31 _H , 34 _H | 14н |

Number of bit access points

Specify the number of device points to be accessed in bit units.

Number of word access points, number of double word access points

Specify the number of device points to be accessed in word unit or double word unit.

Number of blocks

Specify the number of blocks of the device to be accessed in hexadecimal.

Set each number of blocks within the following range.

• Number of word device blocks + Number of bit device blocks \leq 120



In the following case, calculate it as number of blocks \times 2.

• When accessing by setting device extension specification (subcommand: 008□)

Setting method

■Data communication using ASCII code

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

Use capitalized code for alphabetical letter.

■Data communication using binary code

Send the 1-byte^{*1} numerical value (hexadecimal).

*1 The additional code may be added. (Page 19 Additional code (10H))



For 5 points and 20 points

| Number of device points | ASCII code | Binary code |
|-------------------------|--|-------------|
| 5 points | 0 5 30H ₁ 35H | 05н |
| 20 points | 1 4 31 _{H 1} 34 _H | 14н |

Number of word device blocks

Specify the number of blocks of the word device.

Number of bit device blocks

Specify the number of blocks of the bit device.

Read data, write data

The read device value is stored for reading, and the data to be written is stored for writing.

The data order differs between bit units or word units.

For bit units

The following shows the data to be read and written in bit units.

■Data communication using ASCII code

The ON/OFF status of each device are represented with single-digit ASCII code.

For ON: '1' (31H)For OFF: '0' (30H)

■Data communication using binary code

Represent the ON/OFF status of each device in 4-bit per 1 point.

For ON: '1'For OFF: '0'

When the number of points is odd, the lowest 4 bits are set to '0'.

Ex.

When indicating ON/OFF status of five points from M10

| M10 | M11 | M12 | | M13 | M14 |
|--------------------------------------|-----|-----|---------------------------|-------------------|-----|
| ON | OFF | ON | | OFF | ON |
| ASCII code | | | Binary code ^{*1} | | |
| 1 0 1 0 1 31H, 30H, 31H, 30H, 31H | | | DLE DL1 | E DLE 10H 10H 10H | |

^{*1} The additional code may be added. (FP Page 19 Additional code (10H))

For word units (16-point unit for bit device)

The following shows the data to be read and written in word units.

When handling data other than bit data, refer to the following section.

Page 44 Considerations for handling real number data and character string data

■Data communication using ASCII code

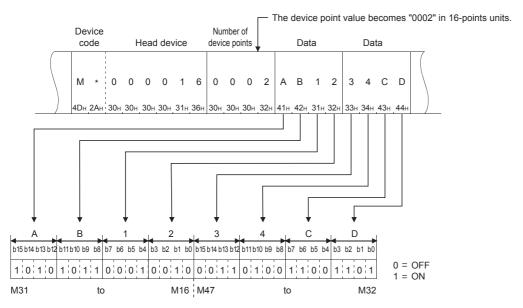
Convert the 1-word(16 points of bit device) numerical value to 4-digit ASCII code (hexadecimal), and send it from the upper digits.

Use capitalized code for alphabetical letter.

The ON/OFF status of bit device is a value of hexadecimal 1-digit in 4-point units.

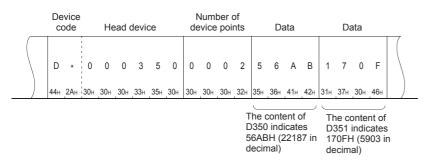


When indicating ON/OFF status of 32 points from M16



Ex.

When indicating the stored data of D350 and D351

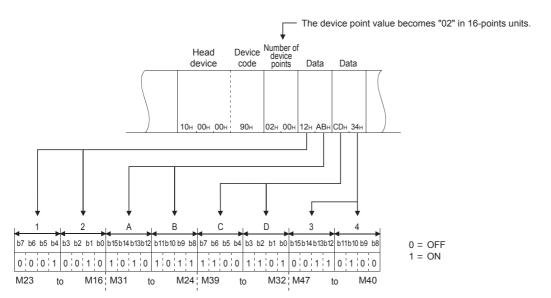


■Data communication using binary code

Send the numerical value in order from the lower byte (L: bit 0 to 7) by handling 16 points unit as 2 bytes.

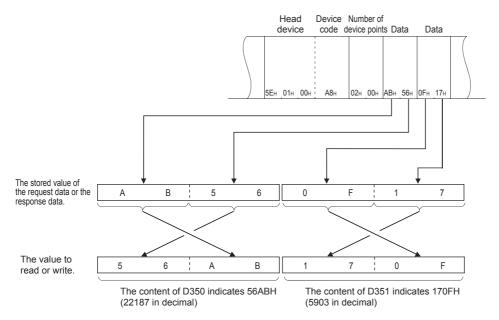


When indicating ON/OFF status of 32 points from M16



Ex.

When indicating the stored data of D350 and D351



For double word unit (32-point unit for bit device)

The following shows the data to be read and written in double word units.

■Data communication using ASCII code

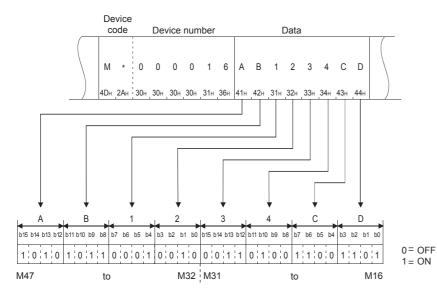
Convert the 2-word numerical value (32 points of bit device) to 8-digit ASCII code (hexadecimal), and send it from the upper digits.

Use capitalized code for alphabetical letter.

The ON/OFF status of the bit device is 1-digit hexadecimal value in 4-point units.

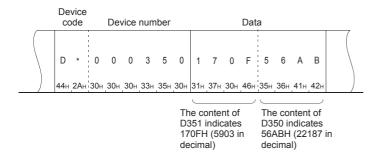


When indicating ON/OFF status of 32 points from M16



Ex.

When indicating the stored data of D350 (D351)

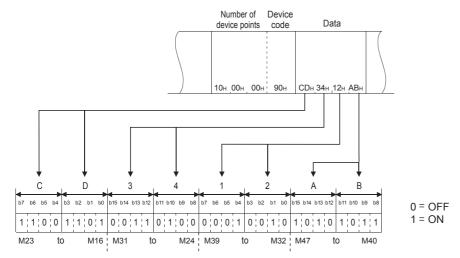


■Data communication using binary code

Send the numerical value in order from the lower byte (L: bit 0 to 7) by handling 32 points unit as 4 bytes.

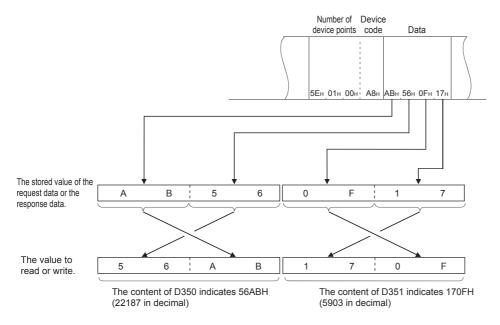


When indicating ON/OFF status of 32 points from M16



Ex.

When indicating the stored data of D350 (D351)



Considerations for handling real number data and character string data

The word data and double word data are handled as integer value (16-bit data or 32-bit data).

When data other than integer (real number, character string) is stored in a device, the stored value is read as integer value.

- When real number (0.75) is stored in D0 and D1: D0 = 0000H, D1 = 3F40H
- When character string ('12AB') is stored in D2 and D3: D2 = 3231H, D3 = 4241H

For data to be used as real number or character string data in the instructions of the programmable controller, write it to the device/label according to the defined data specification method. For more details on how to specify data used in instructions, refer to the MELSEC iQ-F FX5 Programming Manual (Instructions, Standard Functions/Function Blocks).

■For character string data

The following shows how character string data is stored.

| Item | For ASCII code character string | | | | |
|--|---------------------------------------|---|--|--|--|
| Character string to be stored | 'ABC' | 'ABCD' | | | |
| Character code | '41H', '42H', '43H' | '41H', '42H', '43H', '44H' | | | |
| Image when character string data is stored from D0 | NULL indicates 00H. D0 B A D1 NULL C | NULL indicates 00H. D0 B A D1 D C D2 NULL NULL | | | |



Write ASCII code character string data used in the instructions which handle character strings to word device Store the character string ('ABCD') to D0 and D1: D0 = 4241H ('BA'), D1 = 4443H ('DC') Specify the following data for write data.

| ASCII code | Binary code |
|--|---|
| B A D C NULL NULL 4 2 4 1 4 4 3 0 0 0 0 0 34H, 32H 34H, 32H 34H, 33H 30H, 30H, 30H, 30H, 30H D0 D1 D2 | A B C D NULL NULL 00H 10H 10H 10H 10H 10H 10H 10H 10H 10H |



When communicating ASCII code character string data in ASCII code, data is rearranged every two characters and stored.

Device memory extension specification (subcommand: bit7)

For details, refer to Page 85 Device Memory Extension Specification.

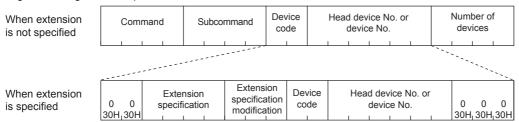
This section explains how to read or write from/to a device to/from module access device areas and how to specify a device indirectly by using index register.

Message format

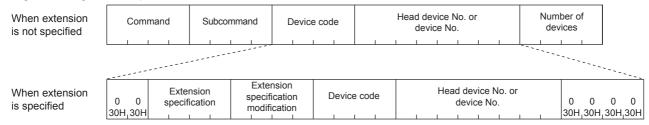
Response messages are extended as well.

■When communicating data in ASCII code

2 digit code/6 digit number specification

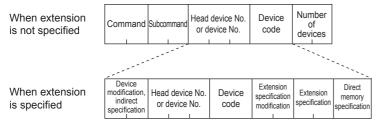


4 digit code/8 digit number specification

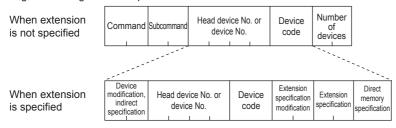


■When communicating data in binary code

2 digit code/6 digit number specification

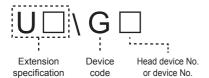


4 digit code/8 digit number specification



2 Module access device specification

The following shows the approach for module access device specification in programming and request data.



■Extension specification

Specify the module number of intelligent function modules.

| ASCII code | Binary code | | |
|---|--|--|--|
| Specify the module number in hexadecimal (3-digit ASCII code). When described with 4-digits, specify the module number with the upper 3-digits. | Specify the module number in hexadecimal (2 bytes). When described with 4-digits, specify the module number with the upper 3-digits. | | |
| Example 001 | Example 001 | | |
| U | | | |

■Device code

Specify the module access device in the device code list.

■Head device No. or device No.

The format is the same as the message when extension is not specified.

■Direct memory specification (only when communicating in binary code)

The type (intelligent function module device) of access device is specified.

Module access device: F8H is specified

Set/reset

Specify the ON/OFF status of bit device.

• For ON: '1'

| Device specification format of subcommand | ASCII code | Binary code |
|---|-------------------------------|-------------|
| 2 digit code/6 digit number specification | 0 1 30H ₁ 31H | 01н |
| 4 digit code/8 digit number specification | 0 0 0 1 30H, 30H, 30H, 31H | 01н , 00н |

• For OFF: '0'

| Device specification format of subcommand | ASCII code | Binary code |
|---|-------------------------------|-------------|
| 2 digit code/6 digit number specification | 0 0 30H ₁ 30H | 00н |
| 4 digit code/8 digit number specification | 0 0 0 0 30H, 30H, 30H, 30H | 00н , 00н |

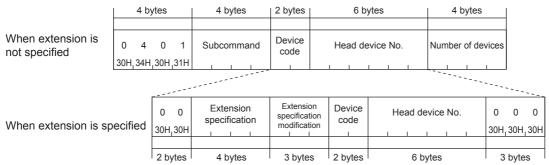
Device Read (Batch)

Data in devices are read in a batch.

Request data

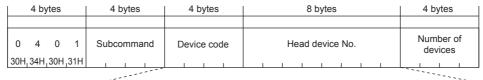
■When communicating data in ASCII code

2 digit code/6 digit number specification



4 digit code/8 digit number specification

When extension is not specified

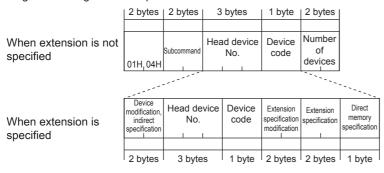


When extension is specified

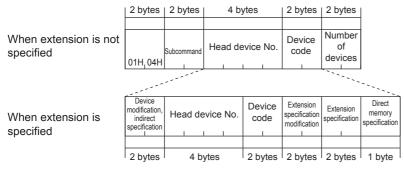
| | 0 0 | Extension specification | Extension specification | Device code | Head device No. | 0 0 0 0 |
|---|----------------------|-------------------------|-------------------------|-------------|-----------------|-----------------|
| d | 30H ₁ 30H | | modification | 1 1 1 | | 30H,30H,30H,30H |
| | | | | | | |
| | 2 bytes | 4 bytes | 4 bytes | 4 bytes | 10 bytes | 4 bytes |

■When communicating data in binary code

2 digit code/6 digit number specification



4 digit code/8 digit number specification



■Subcommand

Specify the subcommand selected from the item.

| Item | | | Subcom | mand | | | | |
|-------------------------|-----------------------------|---------------------------------------|----------------------------------|------------|--------------|-------------|--------|------|
| Data size specification | Device specification format | Device memory extension specification | ASCII co (Upper o characte | column: ch | aracters, lo | wer column: | Binary | code |
| Bit units | 2 digit code/6 digit number | Not specified | 0 | 0 | 0 | 1 | 01H | 00H |
| | specification | | 30H | 30H | 30H | 31H | | |
| | | Specified | 0 | 0 | 8 | 1 | 81H | 00H |
| | | | 30H | 30H | 38H | 31H | | |
| | 4 digit code/8 digit number | Specified | 0 | 0 | 8 | 3 | 83H | 00H |
| | specification | | 30H | 30H | 38H | 33H | 1 | |
| Word units | 2 digit code/6 digit number | Not specified | 0 | 0 | 0 | 0 | 00H | 00H |
| | specification | | 30H | 30H | 30H | 30H | 1 | |
| | | Specified | 0 | 0 | 8 | 0 | 80H | 00H |
| | | | 30H | 30H | 30H | 30H | 1 | |
| | 4 digit code/8 digit number | Specified | 0 | 0 | 8 | 2 | 82H | 00H |
| | specification | | 30H | 30H | 38H | 32H |] | |

■Device code

Specify the device code that corresponds to the device type to be read. Refer to the device code list (Fig. Page 35). The double word device and the long index register (LZ) are not supported.

■Device No.

Specify the head number of target device of reading.

■Number of devices

Specify the number of target device points of reading.

| Item | Number of devices | |
|---------------------------------|-------------------|------------------|
| | ASCII code | Binary code |
| When reading data in bit units | 1 to 3584 points | 1 to 3584 points |
| When reading data in word units | 1 to 960 points | 1 to 960 points |

Response data

The read device value is stored in hexadecimal. The data order differs depending on the type of code, ASCII code or binary code.

Read data

Communication example

■When reading data in bit units

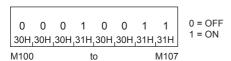
M100 to M107 are read.

· When communicating data in ASCII code

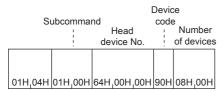
(Request data)

| | | | | | Sı | ıbcoı | mmaı | nd | | vice de | | Hea | ad de | evice | No. | | Num | ber | of de | vices |
|-----|-------|-----|------|-----|-----|-------|------|------|-----|------------|-----|------|-------|-------|-----|------|-----|-----|-------|-------|
| 0 | 4 | | 0 | 1 | 0 | 0 | 0 | 1 | М | * | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 8 |
| 301 | H,34l | 1,3 | 0H,3 | 31H | 30H | 30H | ,30H | ,31H | 4DH | 2AH | 30H | ,30H | ,30H | ,31H | 30H | ,30H | 30H | 30H | ,30H | .38H |

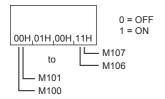
(Response data)



• When communicating data in binary code (Request data)



(Response data)



■When reading data in word units (bit device)

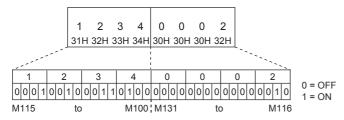
M100 to M131 (2-word) are read.

When communicating data in ASCII code

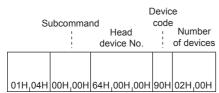
(Request data)

| | | | | Sı | ıbcon | nmar | nd | | vice de | | Hea | nd de | vice l | No. | | Num | ber c | of dev | /ices |
|-----|-----|-----|-----|-----|-------|------|-----|-----|------------|-----|-----|-------|--------|-----|-----|-----|-------|--------|-------|
| 0 | 4 | 0 | 1 | 0 | 0 | 0 | 0 | М | * | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 2 |
| 30H | 34H | 30H | 31H | 30H | 30H | 30H | 30H | 4DH | 2AH | 30H | 30H | 30H | 31H | 30H | 30H | 30H | 30H | 30H | 32H |

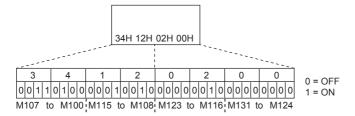
(Response data)



• When communicating data in binary code (Request data)



(Response data)



■When reading data in word units (word device)

Values in T100 to T102 are read.

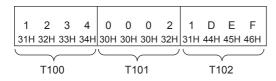
It is supposed that 4660(1234H) is stored in T100, 2(2H) is stored in T101, and 7663(1DEFH) is stored T102.

• When communicating data in ASCII code

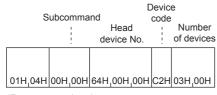
(Request data)

| | | | | Su | ıbcon | nmar | nd | | vice de | | Hea | ad de | vice l | No. | | Num | ıber c | of dev | /ices |
|-----|-----|------|------|-----|-------|------|------|-----|------------|-----|------|-------|--------|-----|-----|-----|--------|--------|-------|
| 0 | 4 | 0 | 1 | 0 | 0 | 0 | 0 | Т | N | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 3 |
| 30H | 34H | ,30H | ,31H | 30H | 30H | ,30H | ,30H | 54H | 4EH | 30H | ,30H | ,30H | 31H | 30H | 30H | 30H | 30H | 30H | 33H |

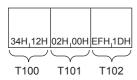
(Response data)



• When communicating data in binary code (Request data)



(Response data)



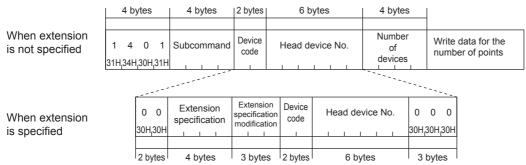
Device Write (Batch)

Data in devices are written in a batch.

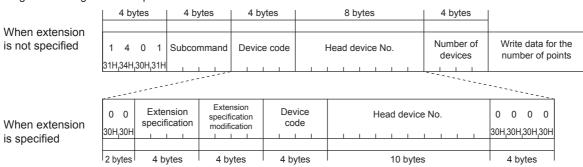
Request data

■When communicating data in ASCII code

2 digit code/6 digit number specification

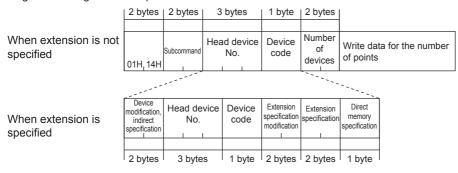


4 digit code/8 digit number specification

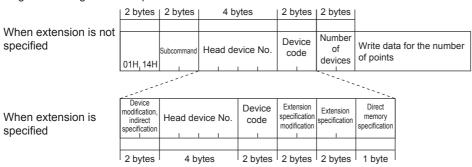


■When communicating data in binary code

2 digit code/6 digit number specification



4 digit code/8 digit number specification



■Subcommand

Specify the subcommand selected from the item.

| Item | | | Subcomn | nand | | | | |
|-------------------------|-----------------------------|---------------------------------------|------------------------|------------|-------------|------------|-----------|-----|
| Data size specification | Device specification format | Device memory extension specification | ASCII cod (Upper co | lumn: char | acters, low | er column: | Binary co | ode |
| Bit units | 2 digit code/6 digit number | Not specified | 0 | 0 | 0 | 1 | 01H | 00H |
| | specification | | 30H | 30H | 30H | 31H | | |
| | | Specified | 0 | 0 | 8 | 1 | 81H | 00H |
| | | | 30H | 30H | 38H | 31H | | |
| | 4 digit code/8 digit number | Specified | 0 | 0 | 8 | 3 | 83H | 00H |
| | specification | | 30H | 30H | 38H | 33H | 1 | |
| Word units | 2 digit code/6 digit number | Not specified | 0 | 0 | 0 | 0 | 00H | 00H |
| | specification | | 30H | 30H | 30H | 30H | 1 | |
| | | Specified | 0 | 0 | 8 | 0 | 80H | 00H |
| | | | 30H | 30H | 38H | 30H | 1 | |
| | 4 digit code/8 digit number | Specified | 0 | 0 | 8 | 2 | 82H | 00H |
| | specification | | 30H | 30H | 38H | 32H | 1 | |

■Device code

Specify the device code that corresponds to the device type to be written. Refer to the device code list (Fig. Page 35). The double word device and the long index register (LZ) are not supported.

■Device No.

Specify the head number of target device of writing.

■Number of devices

Specify the number of target device points of writing.

| Item | Number of devices | |
|---------------------------------|-------------------|------------------|
| | ASCII code | Binary code |
| When writing data in bit units | 1 to 3584 points | 1 to 3584 points |
| When writing data in word units | 1 to 960 points | 1 to 960 points |

■Write data

Specify value to be written to a device for the number of points specified in "Device point".

Response data

There is no response data for the Device Write command.

Communication example

■When writing data in bit units

Values are written to M100 to M107.

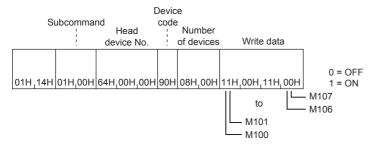
· When communicating data in ASCII code

(Request data)

| | | | | S | ubco | mma | nd | | vice de | | Не | ad de | vice | No. | | Num | ber c | of dev | ices | | | ١ | Vrite | data | | | |
|---|---|---|---|---|------|-----|----|---|------------|-----|----|-------|------|-----|---|-----|-------|--------|------|---|---|---|-------|------|---|---|-----|
| 1 | 4 | 0 | 1 | 0 | 0 | 0 | 1 | М | * | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 8 | 1 | 1 | 0 | 0 | 1 | 1 | 0 | 0 |
| | | | | 1 | | | | 1 | | l . | | | | | | ı | | | | | | | | | | | 30H |

M100 to M107 0 = OFF

 When communicating data in binary code (Request data)



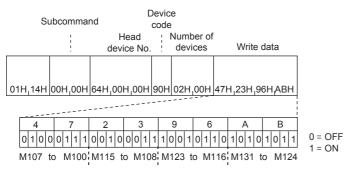
■When writing data in word units (bit device)

Values are written to M100 to M131 (2-word).

• When communicating data in ASCII code (Request data)

| | | | | S | ubco | mma | nd | | vice de | | He | ad de | evice | No. | | Num | ber c | of dev | vices | | | ٧ | Vrite | data | | | | |
|-----|--------------------|---|------------------|-----|------|-----|----|---|------------|---|----|-------|-------|-----|----------|-----|-------|------------|-------|----------|-------|----|------------|-------|-----------|----|------------|-------|
| 1 | 4 | 0 | 1 | 0 | 0 | 0 | 0 | М | * | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 2 | 2 | 3 | 4 | 7 | Α | В | 9 | 6 | |
| 31F | 1 _. 34H | - | ₁ 31H | 30H | - | | | 1 | | - | | | | | | 1 | | | | | - | | - | | _ | - | ,36H | |
| | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | 0 | 2 0 1 | 000 | 3 1 | 4 0 1 0 | 000 | 7 111 | 1 1 0 | | B 1 0 1 | 1 1 1 | 9 0 0 | 10 | 6 1 1 0 | 0 = 0 |
| | | | | | | | | | | | | | | M | 115 | | tc |) | | M100 | , M1 | 31 | | to | | | M116 | 1 = 0 |

 When communicating data in binary code (Request data)



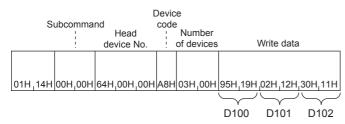
■When writing data in word units (word device)

6549(1995H) is written in D100, 4610(1202H) is written in D101, and 4400(1130H) is written in D102.

• When communicating data in ASCII code (Request data)

| | | | | S | ubco | mma | ınd | | vice de | | Hea | ad de | vice | No. | Nun | nber | of de | vices | | | | W | /rite o | data | | | | |
|----------|-------------------------|-----------|-------------------------|---|------|-----|-----|-----|------------|---|-----|-------|------|-----|-----|------|-------|-------|---|----|-----|---|---------|------|--|----|-----|-------------------------|
| 1 31H | 4 1 _, 34H | 0 ,30H | 1 I _, 31H | 1 | | | | l . | | 1 | | | | | | | | | 1 | | | | | | | | | 0 I ₁ 30H |
| | | | | | | | | | | | | | | | | | | | | D' | 100 | | D1 | 01 | | D. | 102 | |

 When communicating data in binary code (Request data)

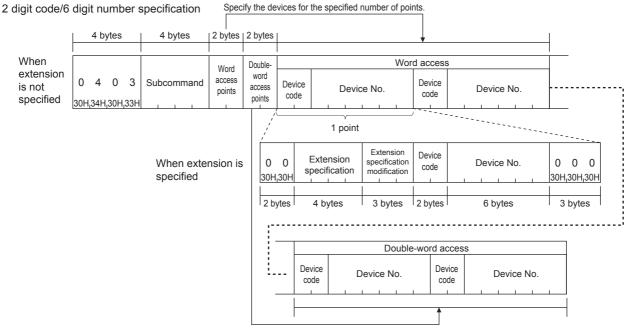


Random read

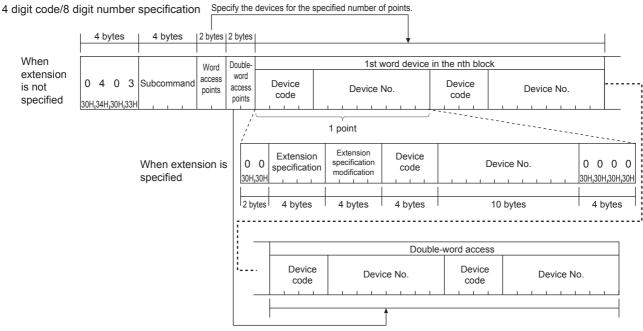
This command specifies the device No. randomly and reads the device value.

Request data

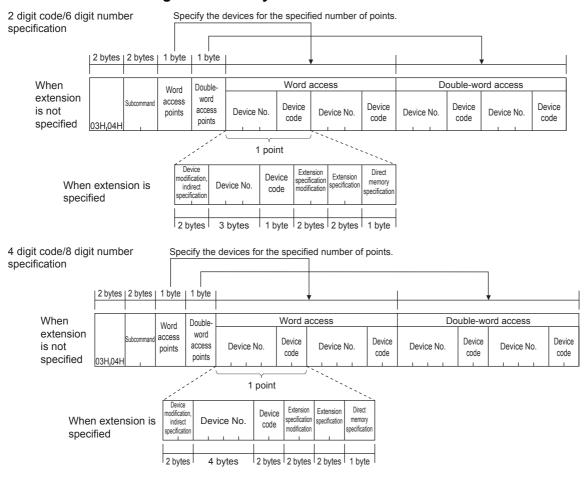
■When communicating data in ASCII code



Specify the devices for the specified number of points.



■When communicating data in binary code



■Subcommand

Specify the subcommand selected from the item.

| Item | | | Subcomm | nand | | | | |
|-------------------------|-----------------------------|---------------------------------------|-------------------------------------|------------|--------------|------------|-----------|-----|
| Data size specification | Device specification format | Device memory extension specification | ASCII cod (Upper co character | lumn: char | acters, lowe | er column: | Binary co | de |
| Word units | 2 digit code/6 digit number | Not specified | 0 | 0 | 0 | 0 | 00H | 00H |
| | specification | | 30H | 30H | 30H | 30H | | |
| | | Specified | 0 | 0 | 8 | 0 | 80H | 00H |
| | | | 30H | 30H | 38H | 30H | | |
| | 4 digit code/8 digit number | Specified | 0 | 0 | 8 | 2 | 82H | 00H |
| | specification | | 30H | 30H | 38H | 32H | 1 | |

■Word access points, double-word access points

Specify the number of target device points of reading.

| Item | Description | Number of points | |
|---------------------------|--|---|----------------------------------|
| | | ASCII code | Binary code |
| Word access points | Specify the number of points to be accessed in one-word units. The bit device is 16-point units, the word device is one-word units. | 1 ≤ word access points + doub When device memory extension | on specification is used, double |
| Double-word access points | Specify the number of points to be accessed in two-word units. The bit device is 32-point units, the word device is two-word units. | the number of the access point | ts. |

■Device code, device No.

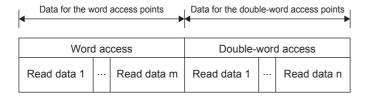
Specify the target device of reading.

| Item | Description |
|--------------------|---|
| Word access | Specify the device points specified as word access points. The specification is not necessary when the word access points are zero. |
| Double-word access | Specify the device points specified as double-word access points. The specification is not necessary when the double-word access points are zero. |

Set up in order of word access device \rightarrow double word access device.

Response data

The read device value is stored in hexadecimal. The data order differs depending on the type of code, ASCII code or binary code.



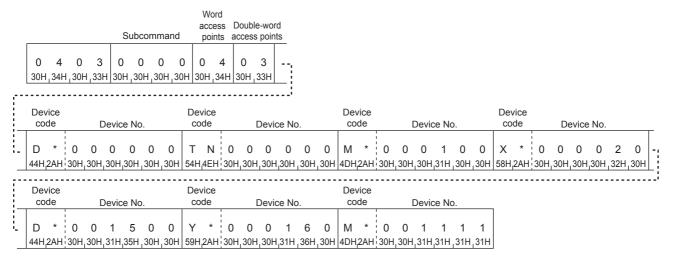
Communication example

Read D0, T0, M100 to M115, X20 to X37 by word access, and D1500 to D1501, Y160 to Y217, M1111 to M1142 by double-word access.

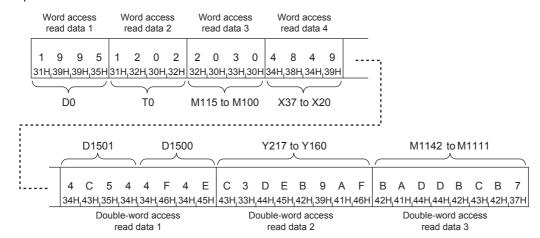
It is supposed that 6549(1995H) is stored in D0, 4610(1202H) is stored in T0, 20302(4F4EH) is stored in D1500, 19540(4C54H) is stored in D1501.

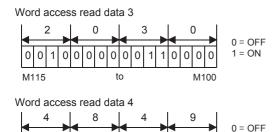
■When communicating data in ASCII code

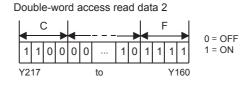
· Request data

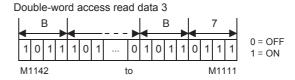


· Response data









■When communicating data in binary code

0

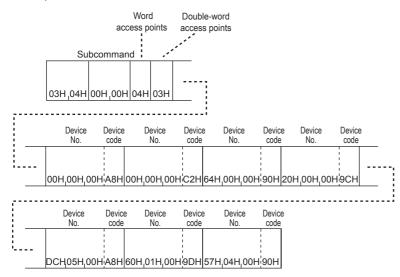
· Request data

0 0

0 0 0 0

to

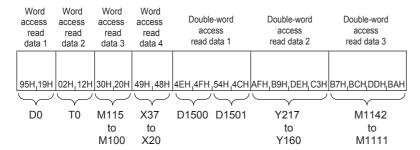
0



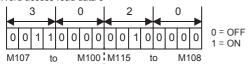
X20

1 = ON

· Response data



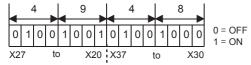
Word access read data 3



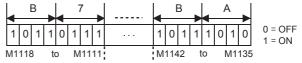
Double-word access read data 2



Word access read data 4



Double-word access read data 3



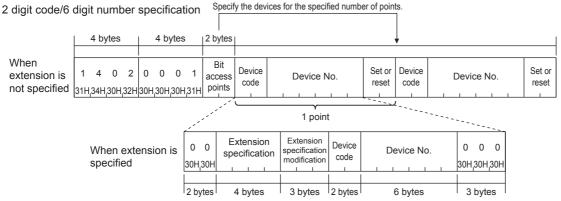
Random write

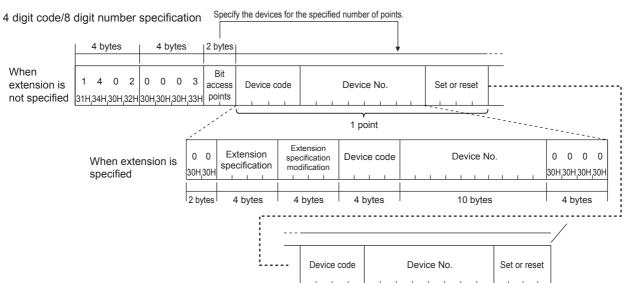
This command specifies the device No. randomly and writes the data.

Request data

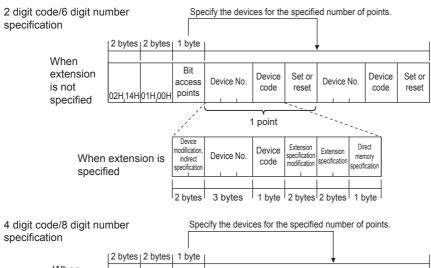
■When writing data in bit units

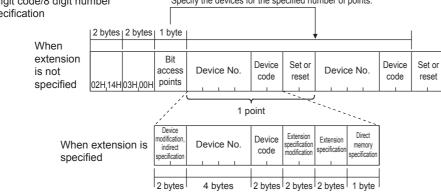
· When communicating data in ASCII code





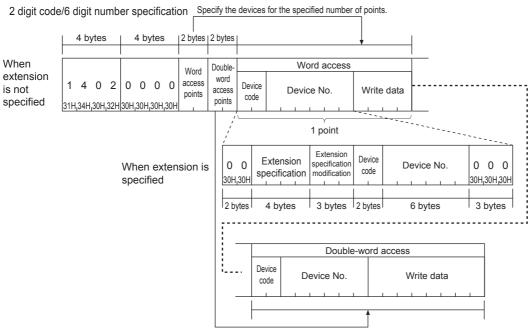
· When communicating data in binary code



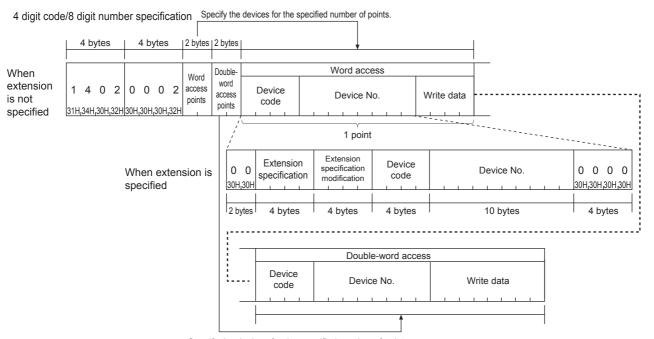


■When writing data in word units

· When communicating data in ASCII code

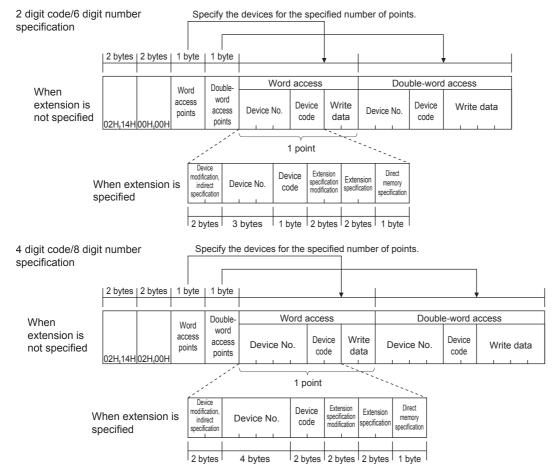


Specify the devices for the specified number of points.



Specify the devices for the specified number of points.

· When communicating data in binary code



■Subcommand

Specify the subcommand selected from the item.

| Item | | | Subcommand | | | | | | | | | |
|-------------------------|---|---------------------------------------|---|-----|-----|-----|-----|-----|--|--|--|--|
| Data size specification | Device specification format | Device memory extension specification | ASCII code (Upper column: characters, lower column: character code) | | | | | | | | | |
| Bit units | 2 digit code/6 digit number | Not specified | 0 | 0 | 0 | 1 | 01H | 00H | | | | |
| | specification | | 30H | 30H | 30H | 31H | | | | | | |
| | | Specified | 0 | 0 | 8 | 1 | 81H | 00H | | | | |
| | | | 30H | 30H | 38H | 31H | | | | | | |
| | 4 digit code/8 digit number specification | Specified | 0 | 0 | 8 | 3 | 83H | 00H | | | | |
| | | | 30H | 30H | 38H | 33H | | | | | | |
| Word units | 2 digit code/6 digit number | Not specified | 0 | 0 | 0 | 0 | 00H | 00H | | | | |
| | specification | | 30H | 30H | 30H | 30H | | | | | | |
| | | Specified | 0 | 0 | 8 | 0 | 80H | 00H | | | | |
| | | | 30H | 30H | 38H | 30H | 1 | | | | | |
| | 4 digit code/8 digit number | Specified | 0 | 0 | 8 | 2 | 82H | 00H | | | | |
| | specification | | 30H | 30H | 38H | 32H | 1 | | | | | |

■Bit access points, word access points, double-word access points

| Item | Description | Number of points | | | | | | |
|-------------------|---|---|-------------------------|--|--|--|--|--|
| | | ASCII code | Binary code | | | | | |
| Bit access points | Specify the number of bit device points in one-point units. | 1 to 188 When device memory extension 1 to 94 | n specification is used | | | | | |

| Item | Description | Number of points | | | |
|---------------------------|--|---|-------------|--|--|
| | | ASCII code | Binary code | | |
| Word access points | Specify the number of points to be accessed in one-word units. The bit device is 16-point units, the word device is one-word units. | 1 ≤ word access points × 12 + c ≤ 1920 | • | | |
| Double-word access points | Specify the number of points to be accessed in two-word units. The bit device is 32-point units, the word device is two-word units. | When device memory extension specification is used, double the number of the access points. | | | |

■Device code, device No., write data

Specify the target device of writing.

The data is specified in hexadecimal number.

| Item | Description |
|--------------------|---|
| Word access | Specify the device points specified as word access points. The specification is not necessary when the word access points are zero. |
| Double-word access | Specify the device points specified as double-word access points. The specification is not necessary when the double-word access points are zero. |

■Set or reset

Specify ON/OFF of the bit device.

• 2 digit code/6 digit number specification

| Item | Data to write | | Remark |
|-------------|---------------|------|---|
| | ON | OFF | |
| ASCII code | "01" | "00" | Two characters will be sent in order from "0". |
| Binary code | 01H | 00H | The one-byte numerical value shown left will be sent. |

• 4 digit code/8 digit number specification

| Item | Data to write | | Remark |
|-------------|---------------|--------|---|
| | ON | OFF | |
| ASCII code | "0001" | "0000" | Four characters will be sent in order from "0". |
| Binary code | 0001H | 0000H | The two-byte numerical value shown left will be sent. |

Response data

There is no response data for the Random write command.

Communication example

■When writing data in bit units

Turn off M50 and turn on Y27.

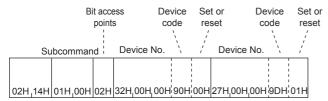
When communicating data in ASCII code
(Degreest data)

(Request data)

| | | | | | | | | Е | 3it | | | | | | | | | | | | | | | | | | | | |
|-----|------|------|------|-----|-------|------|------|-----|------|-----|------|-----|------|-------|------|------|------|-----|------|-----|------|----------|------|-------|------|-----|------|-----|------|
| | | | | | | | | acc | cess | Dev | /ice | | | | | | | Set | t or | Dev | vice | | | | | | | Se | t or |
| | | | | Sι | ıbcor | nmar | nd | ро | ints | CO | de | | - 1 | Devic | e No |). | | res | set | CO | de | | | Devic | e No | | | re | set |
| | | | | | | | | | | | | | | | | | | | | | | | | | | | | 1 | |
| 1 | 4 | 0 | 2 | 0 | 0 | 0 | 1 | 0 | 2 | M | * | 0 | 0 | 0 | 0 | 5 | 0 | 0 | 0 | Υ | * | 0 | 0 | 0 | 0 | 2 | 7 | 0 | 1 |
| 31H | ,34H | ,30H | ,32H | 30H | ,30H | ,30H | ,31H | 30H | ,32H | 4DH | 2AH | 30H | ,30H | I,30H | 30H | ,35H | ,30H | 30H | ,30H | 59H | 2AH | ; 30H | ,30H | ,30H | 30H | 32H | ,37H | 30H | 31H |

When communicating data in binary code

(Request data)



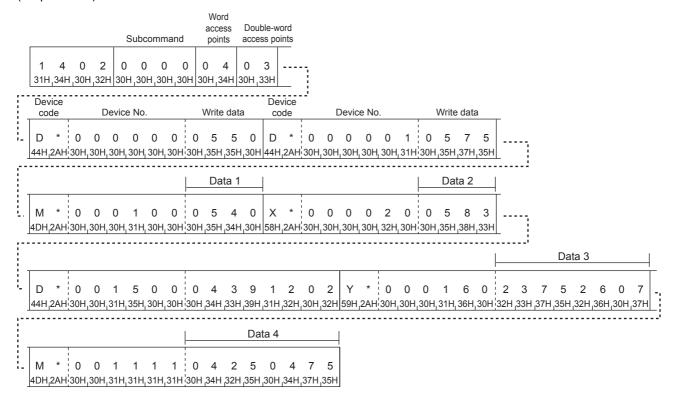
■When writing data in word units

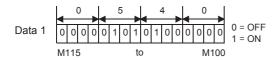
Write the value in a device as follows.

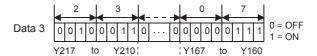
| Item | Target device |
|--------------------|--|
| Word access | D0, D1, M100 to M115, X20 to X37 |
| Double-word access | D1500 to D1501, Y160 to Y217, M1111 to M1142 |

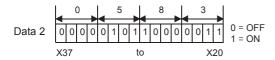
When communicating data in ASCII code

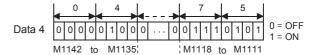
(Request data)



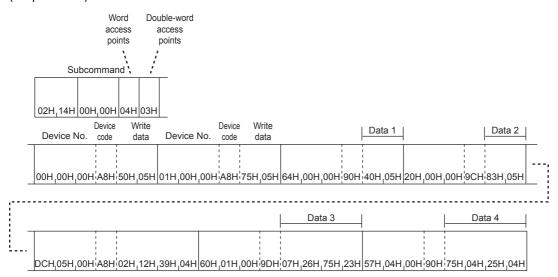


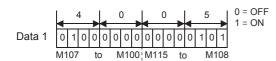


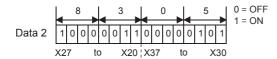


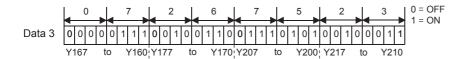


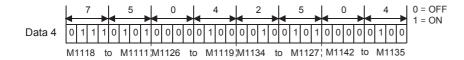
• When communicating data in binary code (Request data)











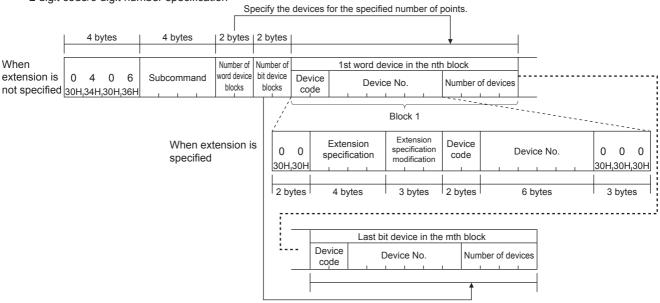
Batch read multiple blocks

The examples shown in this section explain the control procedure for reading by randomly specifying multiple blocks, where 1 block consists of n point(s) of bit device memory (one point is specified by 16-bit) or word device memory (one point is specified by 1-word).

Request data

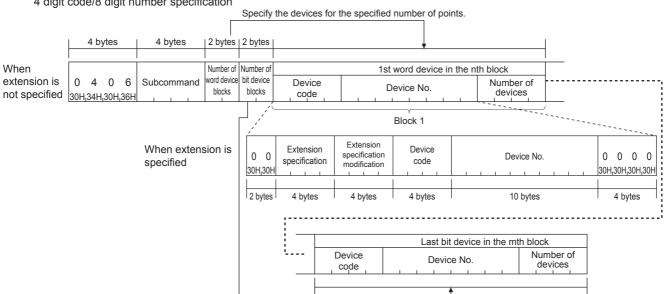
■When communicating data in ASCII code

2 digit code/6 digit number specification

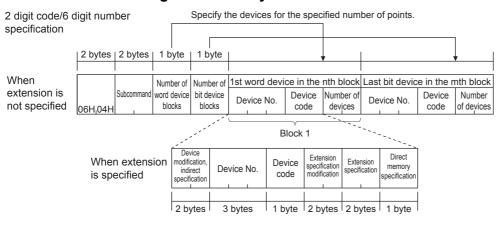


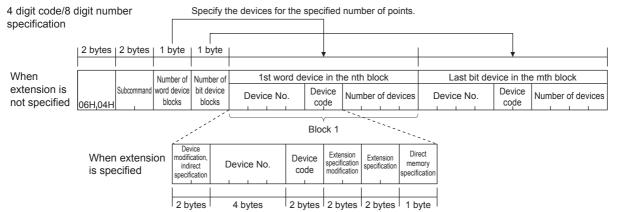
Specify the devices for the specified number of points.

4 digit code/8 digit number specification



■When communicating data in binary code





Subcommand

Specify the subcommand selected from the item.

| Item | | | Subcommand | | | | | | | | |
|-------------------------|-----------------------------|---------------------------------------|---|-----|-----|-----|-----|-----|--|--|--|
| Data size specification | Device specification format | Device memory extension specification | ASCII code (Upper column: characters, lower column: character code) | | | | | | | | |
| Word units | 2 digit code/6 digit number | Not specified | 0 | 0 | 0 | 0 | 00H | 00H | | | |
| | specification | | 30H | 30H | 30H | 30H | | | | | |
| | | Specified | 0 | 0 | 8 | 0 | 80H | 00H | | | |
| | | | 30H | 30H | 38H | 30H | | | | | |
| | 4 digit code/8 digit number | Specified | 0 | 0 | 8 | 2 | 82H | 00H | | | |
| | specification | | 30H | 30H | 38H | 32H | | | | | |

2 Number of word device blocks and number of bit device blocks

Specify the number of blocks of the device to be read in hexadecimal.

| Item | Description | Number of points | | | | |
|------------------------------|---|--|-------------|--|--|--|
| | | ASCII code | Binary code | | | |
| Number of word device blocks | Specify the number of blocks of the word device to be read. | Number of word device blocks + r When device memory extension s | | | | |
| Number of bit device blocks | Specify the number of blocks of the bit device to be read. | number of the block points. | | | | |

3 Device code, device No., number of device points

Specify the device points while satisfying the following conditions:

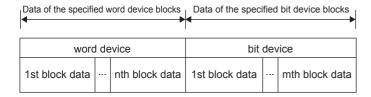
Total number of points for all word device blocks + total number of points for all bit device blocks ≤ 960

| Item | Description |
|-------------|--|
| Word device | Specify the device points specified in "Number of word device blocks". When "Number of word device blocks" is set to 0, this specification is unnecessary. |
| Bit device | Specify the device points specified in "Number of bit device blocks". When "Number of bit device blocks" is set to 0, this specification is unnecessary. |



When specifying a contact or coil of a timer, retentive timer, or counter, use the bit device block. Set up in order of word device \rightarrow bit device.

Response data



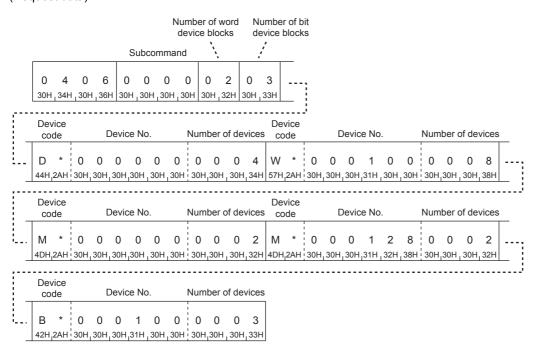
Communication example

Values are read from devices as follows.

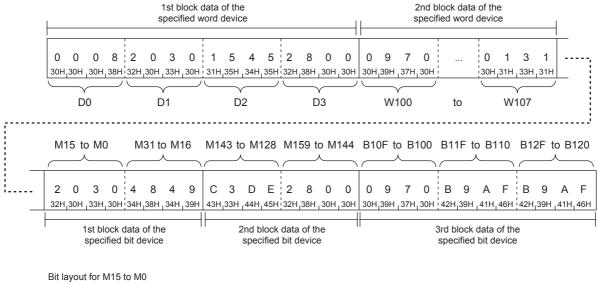
| Item | Read contents |
|-------------|---|
| Word device | Block 1: D0 to D3 (4 points) Block 2: W100 to W107 (8 points) |
| Bit device | Block 1: M0 to M31 (2 points) Block 2: M128 to M159 (2 points) Block 3: B100 to B12F (3 points) |

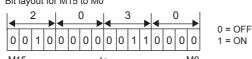
■When communicating data in ASCII code

(Request data)



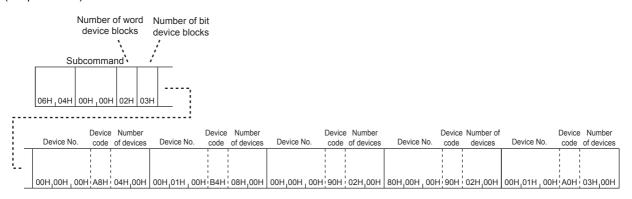
(Response data)



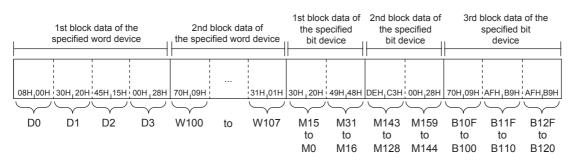


■When communicating data in binary code

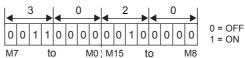
(Request data)



(Response data)



Bit layout for M15 to M0

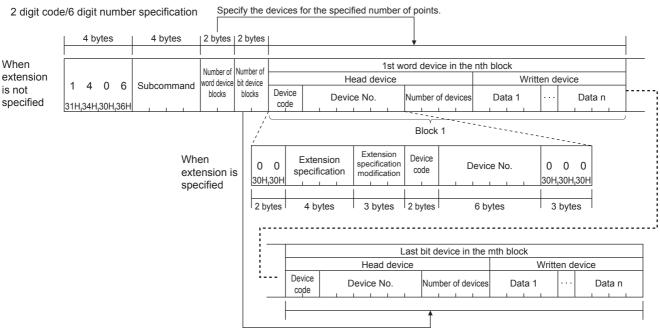


Batch write multiple blocks

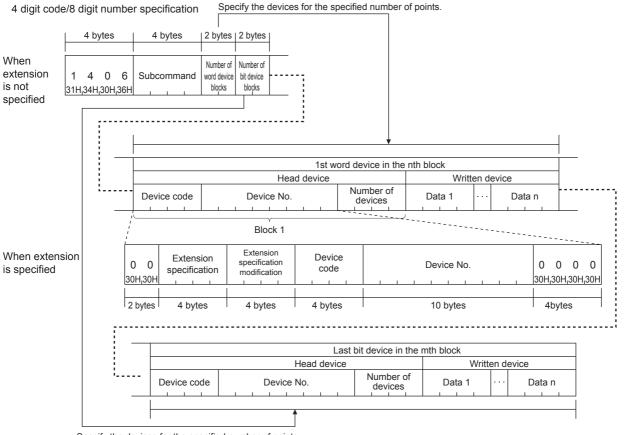
The examples shown in this section explain the control procedure for writing by randomly specifying multiple blocks, where 1 block consists of n point(s) of a bit device memory (one point is specified by 16-bit) and a word device memory (one point is specified by 1-word).

Request data

■When communicating data in ASCII code

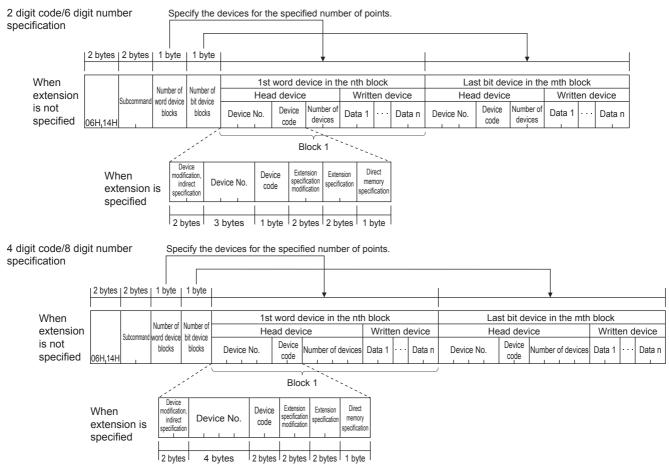


Specify the devices for the specified number of points.



Specify the devices for the specified number of points.

■When communicating data in binary code



Subcommand

Specify the subcommand selected from the item.

| Item Si | | | | Subcommand | | | | | | |
|-------------------------|---|---------------------------------------|---|------------|-----|-----|-------------|-----|--|--|
| Data size specification | Device specification format | Device memory extension specification | ASCII code (Upper column: characters, lower column: character code) | | | | Binary code | | | |
| Word units | 2 digit code/6 digit number | Not specified Specified | 0 | 0 | 0 | 0 | 00H | 00H | | |
| | specification | | 30H | 30H | 30H | 30H |] | | | |
| | | | 0 | 0 | 8 | 0 | 80H | 00H | | |
| | | | 30H | 30H | 38H | 30H | | | | |
| | 4 digit code/8 digit number specification | Specified | 0 | 0 | 8 | 2 | 82H | 00H | | |
| | | | 30H | 30H | 38H | 32H | 1 | | | |

②Number of word device blocks and number of bit device blocks Specify the number of blocks of the device to be written in hexadecimal.

| Item | Description | Number of points | | | | |
|------------------------------|--|--|-------------|--|--|--|
| | | ASCII code | Binary code | | | |
| Number of word device blocks | Specify the number of blocks of the word device to be written. | Number of word device blocks + number of bit device blocks \leq 120 When device memory extension specification is used, double the | | | | |
| Number of bit device blocks | Specify the number of blocks of the bit device to be written. | number of the block points. | | | | |

3 Device code, device No., number of device points

Specify the device points while satisfying the following conditions:

(number of word device blocks + number of bit device blocks) \times 4 + total number of points for all word device blocks + total number of points for all bit device blocks \leq 770

| Item | Description |
|-------------|---|
| Word device | Specify the device of the points specified in "Number of word device blocks". When "Number of word device blocks" is set to 0, this specification is unnecessary. |
| Bit device | Specify the device of the points specified in "Number of bit device blocks". When "Number of bit device blocks" is set to 0, this specification is unnecessary. |



When specifying a contact or coil of a timer, retentive timer, or counter, use the bit device block. Set up in order of word device \rightarrow bit device.

Response data

There is no response data for the batch write multiple blocks command.

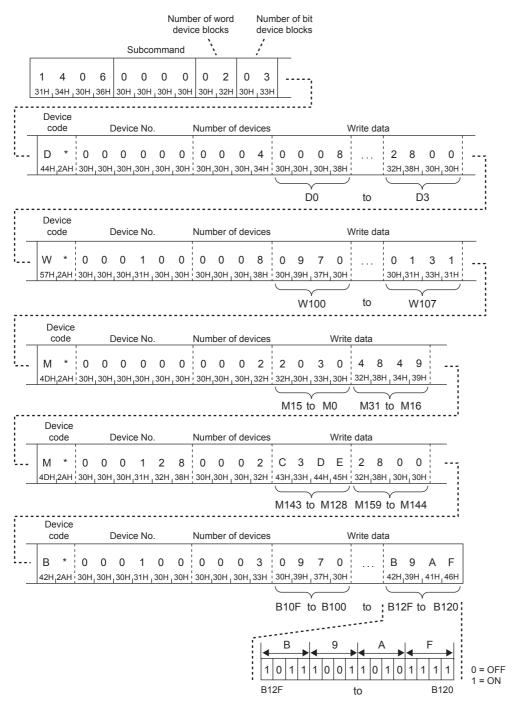
Communication example

Write values from devices as follows.

| Item | Write contents |
|-------------|---|
| Word device | Block 1: D0 to D3 (4 points) Block 2: W100 to W107 (8 points) |
| Bit device | Block 1: M0 to M31 (2 points) Block 2: M128 to M159 (2 points) Block 3: B100 to B12F (3 points) |

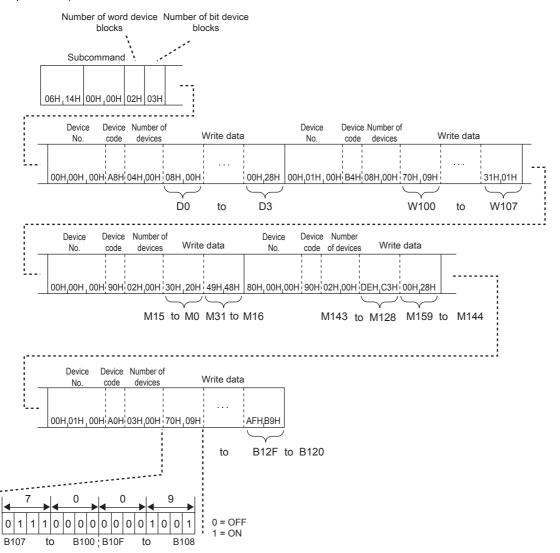
■When communicating data in ASCII code

(Request data)



■When communicating data in binary code

(Request data)



4.3 Remote Control

This section describes the command to set the MC protocol compatible device or CPU module to the RUN status or STOP status by a message from the external device.

Before the remote operation

When the accessed device or module is turned from off to on or the system is reset after the remote operation

The information about the remote operation will be deleted.



Even if the Remote STOP is executed when the switch of the CPU module is in the RUN status, the operation will return to the RUN status after resetting the module.

When a remote password of the CPU module of the access destination is enabled

Remote operation from the external device is not available. An error will occur at the access destination, and an abnormal response will be sent back to the external device. Unlock the remote password of the CPU module side, and resend the request message.

Operable station in one command

Only one station can be operated remotely by one command.

Remote RUN

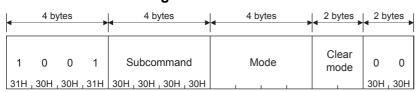
This command executes Remote RUN to the access destination module.



Remote RUN can be executed when the switch of the access destination module is in the RUN status. Even if the switch is in the STOP status, Remote RUN (command: 1001H) will be completed normally. However, the access destination does not change to the RUN status.

Request data

■When communicating data in ASCII code



■When communicating data in binary code

| ŀ | 2 bytes | 2 bytes | 2 bytes | 1 byte | 1 byte |
|---|-----------|------------|---------|---------------|--------|
| | | Subcommand | Mode | Clear mode | |
| | 01H . 10H | 00H . 00H | | | 00H |

■Mode

This mode specifies whether Remote RUN can be executed forcibly by a device other than the external device which performed Remote STOP or Remote PAUSE. If forced execution is not allowed, Remote RUN can be executed only by the external device which performed Remote STOP or Remote PAUSE.

Forced execution is used when the external device which performed the remote operation cannot execute Remote RUN because of a problem with the device.

| Item | Mode | | | | | |
|--|----------------------------|-------------|--|--|--|--|
| | ASCII code | Binary code | | | | |
| Forced execution not allowed (Remote RUN cannot be executed when other device executes Remote STOP or Remote PAUSE.) | 0 0 0 1 30H,30H,30H,31H | 01H,00H | | | | |
| Forced execution allowed (Remote RUN can be executed when other device executes Remote STOP or Remote PAUSE.) | 0 0 0 3 30H,30H,33H | 03Н,00Н | | | | |

■Clear mode

This mode specifies whether the clear (initialization) processing of device is executed when operation starts after Remote RUN.

Only 00H is valid.

| Item | Mode | | | | |
|---------------------|----------------|-------------|--|--|--|
| | ASCII code | Binary code | | | |
| Do not clear device | 0 0 30H,30H | ООН | | | |

Response data

There is no response data for the Remote RUN command.

Communication example

Set mode to "Forced execution not allowed", and set clear mode to "Clear all devices including that in the latch range" when executing Remote RUN.

• When communicating data in ASCII code (Request data)

| | | | | | | | | | M | ode | | | ear ode | | |
|-----|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------------|-----|------|
| 1 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 2 | 0 | 0 |
| 31H | ,30H | 30H | 31H | 30H | 31H | 30H | 32H | 30H | ,30H |

 When communicating data in binary code (Request data)

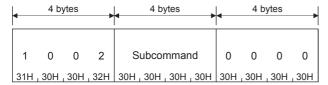
| | | | | Мс | de | Clear mode | |
|-----|------------------|-----|------|-----|-----|---------------|-----|
| | | | | | | | |
| 01H | ₁ 10H | 00H | 100H | 01H | 00H | 02H | 00H |

Remote STOP

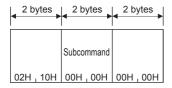
This command executes Remote STOP to the access destination module.

Request data

■When communicating data in ASCII code



■When communicating data in binary code



Response data

There is no response data for the Remote STOP command.

Communication example

Send request messages from the external device by using the message format shown in the request data above.

Remote PAUSE

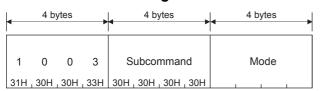
This command executes Remote PAUSE to the access destination module.



Remote PAUSE can be executed when the switch of the access destination module is in the RUN status. Even if the switch is in the STOP status, Remote PAUSE (command: 1003H) will be completed normally. However, the access destination does not change to the PAUSE status.

Request data

■When communicating data in ASCII code



■When communicating data in binary code

| 2 bytes | 2 bytes | 2 bytes |
|----------------------|------------|---------|
| | Subcommand | Mode |
| 03H ₁ 10H | 00H , 00H | 1 |

■Mode

This mode specifies whether Remote PAUSE can be executed forcibly by a device other than the external device which performed Remote STOP or Remote PAUSE. If forced execution is not allowed, Remote PAUSE can be executed only by the external device which performed Remote STOP or Remote PAUSE.

Forced execution is used when the external device which performed the remote operation cannot execute Remote PAUSE because of a problem with the device.

| Item | Mode | | | | | |
|--|----------------------------|-------------|--|--|--|--|
| | ASCII code | Binary code | | | | |
| Forced execution not allowed (Remote RUN cannot be executed when other device executes Remote STOP or Remote PAUSE.) | 0 0 0 1 30H,30H,30H,31H | 01H,00H | | | | |
| Forced execution allowed (Remote RUN can be executed when other device executes Remote STOP or Remote PAUSE.) | 0 0 0 3 30H,30H,30H,33H | 03H,00H | | | | |

Response data

There is no response data for the Remote PAUSE command.

Communication example

Set mode to "Forced execution not allowed" when executing Remote PAUSE.

■When communicating data in ASCII code

(Request data)

| Mode | | | | | | | | | | | |
|------|-----|-----|------|-----|-----|-----|-----|-----|-----|------|------|
| | | | | | | | | | | | |
| 1 | 0 | 0 | 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| 31H | 30H | 30H | ,33H | 30H | 30H | 30H | 30H | 30H | 30H | ,30H | ,31H |

■When communicating data in binary code

(Request data)



Remote latch clear

This command executes remote latch clear to the access destination module.

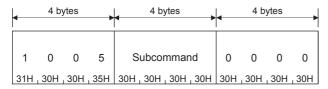


Before executing the remote latch clear, set the status of the access destination module to STOP. While the access destination is stopped or paused remotely by request from another external device:

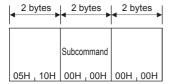
- The remote latch clear cannot be executed. Abnormal completion of the command will occur.
- Cancel the Remote STOP or Remote PAUSE before executing the command.

Request data

■When communicating data in ASCII code



■When communicating data in binary code



Response data

There is no response data for remote latch clear command.

Communication example

Send request messages from the external device by using the message format shown in the request data above.

Remote RESET

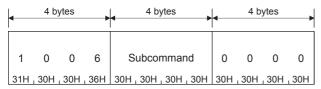
This command executes Remote RESET to the access destination module. Remote RESET is used to restore when an error occurred in the MC protocol compatible device.



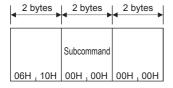
- Before executing Remote RESET, enable Remote RESET if there is a Remote RESET enable/disable setting in the parameter of the access destination
- Before executing Remote RESET, set the status of the access destination module to STOP.
- In some cases, Remote RESET cannot be executed because of hardware error, etc.
- The response message when Remote RESET is executed may not be sent back to the external device since the access destination is reset.

Request data

■When communicating data in ASCII code



■When communicating data in binary code



Response data

There is no response data for the Remote RESET command.

Communication example

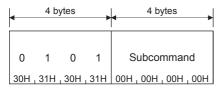
Send request messages from the external device by using the message format shown in the request data above.

Read CPU model nome

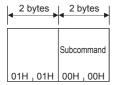
This command reads the processor module name code (processor type) of the access destination module.

Request data

■When communicating data in ASCII code

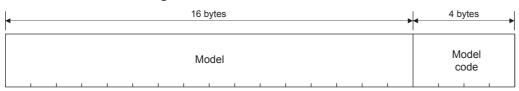


■When communicating data in binary code

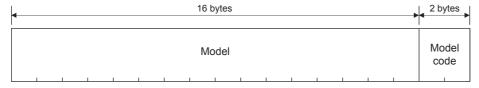


Response data

■When communicating data in ASCII code



■When communicating data in binary code



■Model

The characters of the module model are stored for 16 characters from the upper byte.

If the model to be read is less than 16 characters, space (20H) is stored for the remaining characters. Even when communicating data in binary code, the module model is stored in ASCII code.

■Model code

The following model codes will be stored.

When communicating in binary code, the data is stored in order from the lower byte to the upper byte.

| Model | Model code (hexadecimal) |
|----------------|--------------------------|
| FX5U-32MR/ES | 4A21H |
| FX5U-64MR/ES | 4A23H |
| FX5U-80MR/ES | 4A24H |
| FX5U-32MT/ES | 4A29H |
| FX5U-64MT/ES | 4A2BH |
| FX5U-80MT/ES | 4A2CH |
| FX5U-32MT/ESS | 4A31H |
| FX5U-64MT/ESS | 4A33H |
| FX5U-80MT/ESS | 4A34H |
| FX5UC-32MT/D | 4A91H |
| FX5UC-32MT/DSS | 4A99H |



The model of the CPU module is identified by the model code.

Communication example

■When communicating data in ASCII code

(Request data)

0 1 0 1 0 0 0 0 0 30H,31H,30H,31H 30H,30H,30H,30H

(Response data)

| _ | | _ | | | _ | _ | | _ | | _ | _ | | | | | ١. | | _ | . |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| F | Χ | 5 | U | - | 3 | 2 | M | R | / | Е | S | | | | | 4 | Α | 2 | 1 |
| 46H | 58H | 35H | 55H | 2DH | 33H | 32H | 4DH | 52H | 2FH | 45H | 53H | 20H | 20H | 20H | 20H | 34H | 41H | 32H | 31H |

■When communicating data in binary code

(Request data)



(Response data)

F X 5 U - 3 2 M R / E S 46H,58H,35H,55H,2DH,33H,32H,4DH,52H,2FH,45H,53H,20H,20H,20H,20H,20H

4.4 Clear Error

This function turns off ERR LED of the FX5CPU from the external device and/or initializes the communication error information or error code stored in the buffer memory.

This function is used to initialize the current error information due to an abnormal response for a request message and return it to the normal state or initialize the error code storage area of the buffer memory.

The order and description of the data item differ depending on the frame and pattern in a communication.



This function can be used only for the FX5CPU which is connected with the external device.

This function cannot be used for the FX5CPU of another station via the network system.

The data part of the command and control procedure when the display LEDs of the FX5CPU are turned off and the communication error information is initialized from the external device is described.

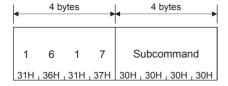
Command

| Function | Command | Processing content | CPU module status | | | | | | |
|-------------|--------------|---|-------------------|---------------------------|------------------------------|--|--|--|--|
| | (Subcommand) | | STOP | RUN | | | | | |
| | | | | Write allow setting | Write prohibit setting | | | | |
| Clear Error | 1617(0000) | Turns off the display LEDs, initializes the error code, and others. | 0 | 0 | 0 | | | | |

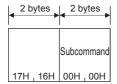
O: The function can be executed.

Request data

■When communicating data in ASCII code



■When communicating data in binary code



Response data

There is no response data for the Clear Error command.

Communication example

Send request messages from the external device by using the message format shown in the request data above.

4.5 Self-Test

This function tests whether the communication function between the external device and FX5CPU operates normally or not. The control procedure when this function is used is described with examples.



- At the startup of the FX5CPU or when trouble occurs, this function can check whether the connection between the external device and FX5CPU is correct and/or whether the data communication function operates normally.
- This function can be used only for the FX5CPU which is connected with the external device (including a multi-drop connection station). This function cannot be used for the FX5CPU of another station via the network system.

Command

| Function | Command | Processing content | CPU module status | | | | | |
|-----------|--------------|---|-------------------|---------------------------|------------------------------|--|--|--|
| | (Subcommand) | | STOP | RUN | | | | |
| | | | | Write allow setting | Write prohibit setting | | | |
| Self-Test | 0619(0000) | Checks whether data communication is executed normally. | 0 | 0 | 0 | | | |

O: The function can be executed.

Request data

■When communicating data in ASCII code

| - | 4 b | ytes | - | 4 bytes | 4 bytes | "n" bytes |
|-----|-----|------|-----|--------------------|-------------------------|---------------|
| 0 | 6 | 1 | 9 | Subcommand | Number of loopback data | Loopback data |
| 30H | 36H | 31H | 39H | 30H, 30H, 30H, 30H | | |

• Number of loopback data (number of bytes)

The number of the bytes is converted into a four-digit ASCII code (hexadecimal) and data is sent from the upper digit ("0").

· Loopback data (user data)

The order of character strings for up to 960 1-byte characters ("0" to "9", "A" to "F") is sent from the head.

■When communicating data in binary code

| 2 bytes | 2 bytes | 2 bytes | "n" bytes |
|-----------|------------|-------------------------|---------------|
| | 1 | | [|
| | Subcommand | Number of loopback data | Loopback data |
| 19H , 06H | 00H , 00H | | |

Number of loopback data (number of bytes)

The two-byte numerical value which indicates the number of the bytes is used and data is sent from the low byte (L: bit 0 to 7).

· Loopback data (user data)

Data is sent for up to 960 bytes from the head by treating each character code ("0" to "9", "A" to "F") as a 1 byte value.

Response data

The same number of the loopback data and loopback data which the external device sent are sent back to the external device.

Communication example

Send request messages from the external device by using the message format shown in the request data (FP Page 83).

■When executing the Self-Test by communicating in ASCII code

(Request data)

| | Com | man | d | Su | bcoı | mma | and | Number of loopback data | | | | | | | | Loc | opba | ack d | ata | | | | |
|-----|--------------------|-----|------------------|-----|------|------|------|-------------------------|-----|-----|-----|-----|-----|-----|-----|-----|------------------|------------------|------------------|------------------|-----|-----|-----|
| 0 | 6 | 1 | 9 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 2 | а | b | С | d | е | f | g | h | i | j | k | ı |
| 30F | I ₁ 36H | 31H | ₁ 39H | 30H | 30H | ,30H | ,30H | 30H | 30H | 31H | 32H | 61H | 62H | 63H | 64H | 65H | ₁ 66H | _. 67H | ₁ 68H | _, 69H | 6AH | 6BH | 6CH |

(Response data)

| | Numb opba | | | | Lo | opba | ick d | lata | | |
|--|--------------|-----------|--|--|----|------|-------|------|--|--|
| | | 2 ,32H | | | | | | | | |

■When executing the Self-Test by communicating in binary code

(Request data)

| С | ommand S | | | | Lo | opba | ıck d | ata | | | | | | | | | |
|---|----------------------|--------|----|-----|-----|------|-------|------------------|-----|-----|------------------|------------------|------------------|-----|-----|-----|-----|
| | | | | | | а | b | С | d | е | f | g | h | i | j | k | ı |
| | 19H ₁ 06H | 00H,00 | 0H | 12H | H00 | 61H | 62H | ₁ 63H | 64H | 65H | ₁ 66H | ₁ 67H | ₁ 68H | 69H | 6AH | 6BH | 6CH |

(Response data)

| Number loopback | | | | | Lo | opba | ick d | lata | | | | |
|----------------------|-----|------|------|------|------|------|-------|------|------|------|------|------|
| 12H ₁ 00H | а | b | с | d | e | f | g | h | i | j | k | I |
| | 61Н | ,62H | ,63Н | ,64H | ,65H | ,66H | ,67H | ,68H | ,69H | ,6AH | ,6BH | ,6CH |

APPENDIX

Appendix 1 Device Memory Extension Specification

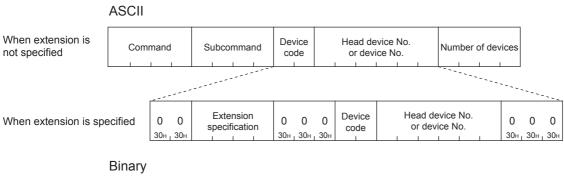
The following accesses are available by setting the subcommand of request data to 008□.

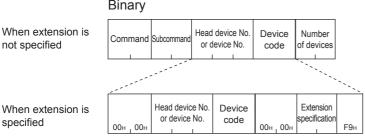
- · Access to module access device
- · Access with indirect specification of the device No. by using index register or long index register
- · Access with indirect specification of the device No. by using values stored in word device

Access to module access device

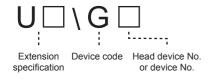
Access to the buffer memory of MC protocol compatible devices or intelligent function modules.

Request data





The following shows the module access device and request data.





Devices described in Page 35 Device number can be accessed by specifying 0 in "extension specification" of commands which can specify multiple devices. However, when specifying 008 in "subcommand", specify the device in the message format shown above. Message formats when extension is not specified and message formats when extension is specified cannot coexist in the same message.

■Command

The following commands can be used for accessing.

| Function | Command |
|-----------------------------|---------|
| Batch read | 0401 |
| Batch write | 1401 |
| Random read | 0403 |
| Random write | 1402 |
| Batch read multiple blocks | 0406 |
| Batch write multiple blocks | 1406 |

■Subcommand

| Subcommand | | | | | | | | |
|----------------------------------|-------------|--|--|--|--|--|--|--|
| ASCII code | Binary code | | | | | | | |
| 0 0 8 0 30H 30H 38H 30H | 80H , 00H | | | | | | | |
| 0 0 8 2 30H, 30H, 38H, 32H | 82H , 00H | | | | | | | |

■Extension specification

Specify the module number of intelligent function modules.

| ASCII code | Binary code | | | |
|--|--|--|--|--|
| Specify the module number in hexadecimal (ASCII code 3-digits). When described with 4-digits, specify the module number with the upper 3-digits. | Specify the module number in hexadecimal (2 bytes). When described with 4-digits, specify the module number with the upper 3-digits. | | | |
| U | Example 001 | | | |

■Device code

Specify the following device codes.

| Туре | Device code | | | Device No. range | | | |
|------|---|---|--|------------------|---|---------|--|
| | ASCII code*1 | | Binary code | | | | |
| | 2 digit code/ 6 digit number specification | 4 digit code/ 8 digit number specification | 2 digit code/ 6 digit 8 digit number number specification specification | | | | |
| Word | G* | G*** | ABH | AB00H | Specify within the device No. range of the module for access destination. | Decimal | |

^{*1} For ASCII codes, the device code is specified with 2 characters. If the device text is one character only, add "*" (ASCII code: 2AH) or a space (ASCII code: 20H) after the device text.

■Head device or device No.

Specify the head device or device No. in decimal, with the same format as the message when extension is not specified.



Indirect specification of the access target device No. can be performed by using the CPU module index register (Z) or long index register (LZ). (Page 88 Access with indirect specification of the device No. by using index register or long index register)

Response data

The same as when extension is not specified.

Communication example

Access to the buffer memory (Address: 1) of the intelligent function module whose module number is 003H.

• When communicating data in ASCII code (Request data)

| S | ubco | mma | ınd | | | | Exte pecif | | | | | | | vice de | | | | evice ice N | | | | | |
|-----|-------|-------|-------|-----|-----|-----|---------------|-------|-------|-----|-------|-----|-----|------------|------|-----|-----|----------------|-------|-----|-----|-------|-----|
| 0 | 0 | 8 | 0 | 0 | 0 | U | 0 | 0 | 3 | 0 | 0 | 0 | G | * | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 |
| 30н | , 30н | , 38н | , 30н | 30н | 30н | 55н | 30н | , 30н | , 33н | 30н | , 30н | 30н | 47н | 2Ан | 30н, | 30н | 30н | 30н | 30н г | 31н | 30н | 30н г | 30н |

• When communicating data in binary code (Request data)

| Subcommand | | | Head device No. or device No. | Device code | S | Extension specification | 1 |
|------------|-----------|-----------|-------------------------------|-------------|-----------|-------------------------|-----------------|
| | 80н . 00н | 00н . 00н | 01н . 00н . 00н | АВн | 00н , 00н | 03н . 00н | F8 _H |

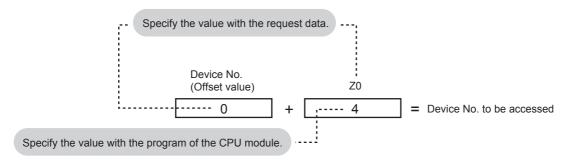
Access with indirect specification of the device No. by using index register or long index register

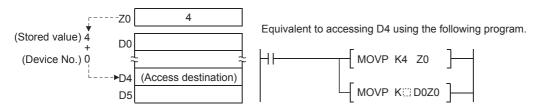
Indirect specification of the device No. can be performed by using the index register or long index register when accessing the device.

The access destination can be switched with one message, by changing the value of the index register or long index register in CPU module programs.



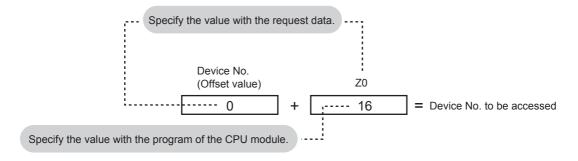
When accessing D4 with D0 and Z0 specifications



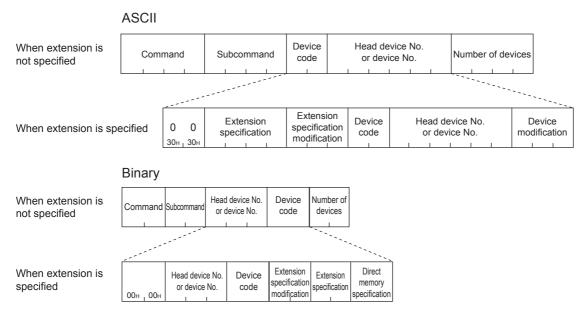


Ex.

When accessing M16 to M31 with M0 and Z0 specifications (Word units)

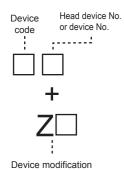


Request data

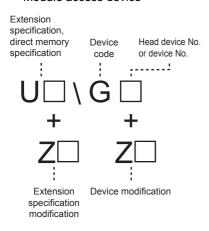


The following shows the approach for devices, index registers, long index registers and request data.

· Other than the module access device



Module access device





When specifying 008 in "subcommand", specify the device with the message format shown above. Message formats when extension is not specified and message formats when extension is specified cannot coexist in the same message.

■Command

The following commands can be used for accessing.

| Function | Command |
|--------------|---------|
| Random read | 0403 |
| Random write | 1402 |

■Subcommand

| Item | Subcommand | | | | | |
|------------------------------|-------------------------------|-------------|--|--|--|--|
| | ASCII code | Binary code | | | | |
| When accessing in bit units | 0 0 8 1 30H, 30H, 38H, 31H | 81H , 00H | | | | |
| When accessing in word units | 0 0 8 0 30H, 30H, 38H, 30H | 80H , 00H | | | | |
| | 0 0 8 2 30H, 30H, 38H, 32H | 82H , 00H | | | | |

■Extension specification

Specify the module number.

The values specified in this item turn to the offset value when performing indirect specification of the module number in "extension specification modification".

| Item | ASCII code | Binary code |
|------------------------------|---|---|
| Module access device | Specify the module number in hexadecimal (2 bytes). | Specify the module number in hexadecimal (2 bytes). |
| | Example 001 U | Example 001 01H ,00H |
| Devices other than the above | Specify 0. 0 0 0 0 30H, 30H, 30H, 30H | Specify 0. |

■Extension specification modification

Treat the value specified in "extension specification" as the offset value. Specify the index register or long index register number when performing indirect specification of the module number with index register or long index register.

• The following value is specified when the access point is a module of the MELSEC iQ-R/iQ-F Series.

| Subcommand | ASCII code | Binary code | | | |
|------------|--|--|--|--|--|
| 0083 | Specify the number of the index register in decimal (2-digit | Specify the number of the index register (Z) in hexadecimal. | | | |
| 0082 | ASCII code). (Specification range: 0 to 24) | (Specification range: 00H to 18H) | | | |
| | Z | □□H, 40H | | | |
| 0081 | Specify the number of the index register in decimal (2-digit | Specify the number of the index register (Z) in hexadecimal. | | | |
| 0080 | ASCII code). (Specification range: 0 to 24) | (Specification range: 00H to 18H) | | | |
| | Z | | | | |

• The following value is specified when the access point is a module of the MELSEC Q/L Series.

| ASCII code | Binary code |
|--|--|
| Specify the number of the index register in decimal (2-digit ASCII code). (Specification range: 0 to 15) | Specify the number of the index register in hexadecimal. (Specification range: 0 to F) |
| Z | □□H ₁ 40H |



The long index register (LZ) can not be used in the extension specification modification.

■Device code

Specify the code of the device to be accessed. (Fig. Page 35 Device code list)

Specify the following device code when accessing the module access device.

| Туре | Device code | | Device No. range | | | |
|------|---|--|------------------|-------|---|---------|
| | ASCII code ^{*1} | | Binary code | | | |
| | 2 digit code/6 digit number specification | 4 digit code/8 digit number specification 4 digit code/8 digit number digit number specification digit code/8 specification | | | | |
| Word | G* | G*** | ABH | AB00H | Specify within the device No. range of the module for access destination. | Decimal |

^{*1} For ASCII codes, the device code is specified with 2 characters. If the device text is one character only, add "*" (ASCII code: 2AH) or a space (ASCII code: 20H) after the device text.

■Head device or device No.

Specify the head device or device No. with the same format as the message when extension is not specified.

The values specified in this item turn to the offset value when performing indirect specification of the device No. in "device modification".

■Device modification

Treat the value specified in "Head device or device No." as the offset value. Specify the index register or long index register number when performing indirect specification of the device No. with index register or long index register.

• The following value is specified when the access point is a module of the MELSEC iQ-R/iQ-F Series.

| Subcommand | ASCII code | Binary code | | |
|------------|---|--|--|--|
| 0083 | Specify the number of the index register in decimal (2-digit | Specify the number of the index register (Z) in hexadecimal. | | |
| 0082 | ASCII code). (Specification range: 0 to 24)*1 | (Specification range: 00H to 18H)*1 | | |
| | Specify the number of the long index register (LZ) in decimal | Specify the number of the long index register (LZ) in | | |
| | (2-digit ASCII code). (Specification range: 0 to 12) | hexadecimal. (Specification range: 00H to 0CH) | | |
| | Z | □□H ₁ 40H | | |
| 0081 | Specify the number of the index register in decimal (2-digit | Specify the number of the index register (Z) in hexadecimal. | | |
| 0800 | ASCII code). (Specification range: 0 to 24) | (Specification range: 00H to 18H) | | |
| | Z | □□H, 40H | | |

^{*1} The device modification range of the index register (Z) is -32768 to 32767. When the device modification range is not within -32768 to 32767, use the long index register (LZ).

 \bullet The following value is specified when the access point is a module of the MELSEC Q/L Series.

| ASCII code | Binary code |
|--|--|
| Specify the number of the index register in decimal (2-digit ASCII code). (Specification range: 0 to 15) | Specify the number of the index register in hexadecimal. (Specification range: 0 to F) |
| Z | □□H, 40H |

■Direct memory specification (only when communicating in binary code)

Specify the device type when accessing the module access device.

| Item | Binary code | | | | | |
|----------------------|--------------|--|--|--|--|--|
| Module access device | Specify F8H. | | | | | |
| Other than the above | Specify 00H. | | | | | |

Response data

The same as when extension is not specified.

Communication example

Accessing the device of D100 + Z4.

· When communicating data in ASCII code

(Request data)

| Subcommand | | | | | Extension specification | | | Extension specification modification | | Device code | | Head device No. or device No. | | | | Device modification | | | | | | | |
|------------|----------|------------|----------|----------|-------------------------|---|--|--------------------------------------|----------|-------------|----------|----------------------------------|--|--|----------|------------------------|----------|-----------------------|----------|----------|-----------|-----------------------|-----------------|
| 0 30н | 0 30н | 8 , 38н | 0 30н | 0 30н | 0 ₁ 30н | _ | | | 0 30н | 0 30н | 0 30н | 0 30н | | | 0 30н | 0 30н | 0 30н | 1 _г 31н | 0 30н | 0 30н | Z 5Ан, | 0 30н _г | 4 34н |

· When communicating data in binary code

(Request data)

| Subcommand | Device modification | Head device No. or device No. | Device code | Extension specification modification | Extension specification | Direct memory specification |
|------------|------------------------|-------------------------------|-------------|--|-------------------------|-----------------------------------|
| 80н , 00н | 04н , 40н | 64н , 00н , 00н | А8н | 00н , 00н | 00н, 00н | 00н |

Access with indirect specification of the device No. by using the values stored in word device

Access the device corresponding to the address stored in word device (for 2 points).

Ex.

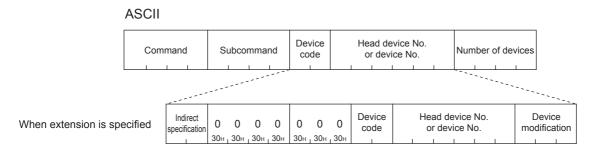
When storing the address of D100 in D0, and trying to access D100 from external devices by accessing "@D0"

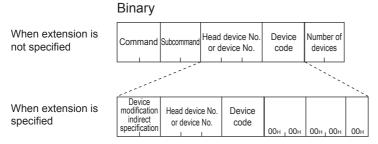
The ADRSET instruction is used on the CPU module side and the address of D100 is stored in D0.



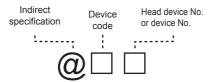
D100 can be indirectly accessed by specifying "@D0" with the request data.

Request data





The following shows the indirect specification devices and request data.





- When specifying 008 in "subcommand", specify the device with the message format shown above.
 Message formats when extension is not specified and message formats when extension is specified cannot coexist in the same message.
- The indirect specification and the device modification using index registers can not be set simultaneously.

■Command

The following commands can be used for accessing.

| Function | Command | | | | | | |
|--------------|---------|--|--|--|--|--|--|
| Random read | 0403 | | | | | | |
| Random write | 1402 | | | | | | |

■Subcommand

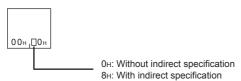
| ASCII code | Binary code | | | | | | |
|-----------------------|-------------|--|--|--|--|--|--|
| 0 0 8 0 | | | | | | | |
| 30н _ 30н _ 38н _ 30н | 80H , 00H | | | | | | |

■Indirect specification, Device modification

Specify the "@" part of the indirect specification device. Indirect specification can be specified only for word devices. When communicating data in ASCII code



When communicating data in binary code



■Device code (Only word device codes can be specified at indirect specification)

Specify the code of the device to be accessed. (Fig. Page 35 Device code list)

■Head device or device No.

Specify the head device or device No. with the same format as the message when extension is not specified.

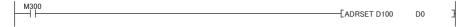
Response data

The same as when extension is not specified.

Communication example

Access to @D0. (Consider @D0 indirect specification of D100.)

At command execution, store the D100 address in D0 with the following programs.



· When communicating data in ASCII code

(Request data)

| Indirect Subcommand specification | | | | | | | | De\ co | | | | | vice l | | | | evice difica | | | | | | |
|-----------------------------------|-----|-----|-----|-----|-----|-----|-----|-----------|-----|-----|-----|-----|--------|-----|-----|-------|------------------|-------|-----|-----|-------|-------|-----|
| 0 | 0 | 8 | 0 | 0 | @ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | D | * | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 30н | 30н | 38н | 30н | 30н | 40н | 30н | 30н | 30н | 30н | 30н | 30н | 30н | 44н | 2Ан | 30н | 30н ј | 30н _І | 30н ј | 30н | 30н | 30н ј | 30н ј | 30н |

· When communicating data in binary code

(Request data)



Appendix 2 CPU Module Processing Time of MC Protocol

When accessing the CPU module from an external device using MC protocol communication, the following "intervention time to the scan time" and "number of scans for processing" of the CPU module side are required. On the request from the external device using MC protocol communication, the CPU module processes a specified number of points during each END processing in case the CPU module is running.

| Item | Command | Subcommand | Access points 1) / 2) | Intervention time (extension of sca | Number of scans | | |
|-----------------------------|---------|------------|--------------------------|-------------------------------------|-----------------|-------------------------|--|
| | | | | Access point 1) | Access point 2) | required for processing | |
| Batch read | 0401 | 0001 | 1/3584 | 0.04 | 0.87 | 1 | |
| | | 0000 | 1/960 | 0.04 | 0.73 | 1 | |
| Batch write | 1401 | 0001 | 1/3584 | 0.04 | 0.95 | 1 | |
| | | 0000 | 1/960 | 0.05 | 0.83 | 1 | |
| Random read | 0403 | 0000 | 1/192 | 0.06 | 2.40 | 1 | |
| Random write | 1402 | 0001 | 1/188 | 0.02 | 1.66 | 1 | |
| | | 0000 | 1/160 ^{*1} | 0.02 | 1.85 | 1 | |
| Batch read multiple blocks | 0406 | 0000 | 1/960 | 0.05 | 0.74 | 1 | |
| Batch write multiple blocks | 1406 | 0000 | 1/960 | 0.04 | 0.67 | 1 | |
| Read CPU model name | 0101 | 0000 | (one station) | 0.03 | _ | 1 | |

^{*1} This is the processing time when accessing with only word access points specified.

^{*2} This is the processing time when 1 is set to [CPU Parameter] - [Service Processing Setting] - [Device/Label Access Service Processing Setting] - [Set Processing Counts] of GX Works3.



· Number of scans required for processing

The CPU module processes only one command during an END processing. If GX Works3 or other modules are also accessing the CPU module simultaneously, the number of scans required for processing may increase due to the waiting time.

• Method of reducing the intervention time to the scan time

Adjust the service process execution count of the CPU module in [CPU Parameter] - [Service Processing Setting] - [Device/Label Access Service Processing Setting] to reduce the intervention time to the scan time. (For details, refer to the MELSEC iQ-F FX5 User's Manual (Application))

· When extension of scan time affects the control

Access multiple times with less points.

INDEX

| 0 to 9 |
|--|
| 1C frame 14 2C frame 14 3C frame 14,24 4C frame 14,23 |
| A |
| Additional code 19 ASCII code 14 |
| <u>B</u> |
| Binary code |
| C |
| Connected station (host station) |
| <u>D</u> |
| Device codes |
| E |
| Error code |
| F |
| Format 14 Format 1 15 Format 4 16 Format 5 17 Frame 14 Frame ID No. 20 |
| L |
| Link time |
| M |
| MC protocol8MC protocol-compatible device8Message format15Module access device8 |
| N |
| Network No |
| 0 |
| Other station |

| P | |
|---|---|
| | PC No |
| R | ! |
| S | Relay station |
| | Self-station No. .28 SLMP .8 SLMP-compatible device .8 Station No. .25 Sum check code .20 |

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REVISIONS

| Revision date | Revision | Description |
|---------------|----------|---------------|
| February 2015 | Α | First Edition |

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WARRANTY

Please confirm the following product warranty details before using this product.

Gratis Warranty Term and Gratis Warranty Range

If any faults or defects (hereinafter "Failure") found to be the responsibility of Mitsubishi occurs during use of the product within the gratis warranty term, the product shall be repaired at no cost via the sales representative or Mitsubishi Service Company. However, if repairs are required onsite at domestic or overseas location, expenses to send an engineer will be solely at the customer's discretion. Mitsubishi shall not be held responsible for any re-commissioning, maintenance, or testing on-site that involves replacement of the failed module.

[Gratis Warranty Term]

The gratis warranty term of the product shall be for one year after the date of purchase or delivery to a designated place. Note that after manufacture and shipment from Mitsubishi, the maximum distribution period shall be six (6) months, and the longest gratis warranty term after manufacturing shall be eighteen (18) months. The gratis warranty term of repair parts shall not exceed the gratis warranty term before repairs.

[Gratis Warranty Range]

- The range shall be limited to normal use within the usage state, usage methods and usage environment, etc., which follow the conditions and precautions, etc., given in the instruction manual, user's manual and caution labels on the product.
- 2) Even within the gratis warranty term, repairs shall be charged for in the following cases.
 - Failure occurring from inappropriate storage or handling, carelessness or negligence by the user. Failure caused by the user's hardware or software design.
 - b) Failure caused by unapproved modifications, etc., to the product by the user.
 - c) When the Mitsubishi product is assembled into a user's device, Failure that could have been avoided if functions or structures, judged as necessary in the legal safety measures the user's device is subject to or as necessary by industry standards, had been provided.
 - d) Failure that could have been avoided if consumable parts (battery, backlight, fuse, etc.) designated in the instruction manual had been correctly serviced or replaced.
 - Relay failure or output contact failure caused by usage beyond the specified life of contact (cycles).
 - f) Failure caused by external irresistible forces such as fires or abnormal voltages, and failure caused by force majeure such as earthquakes, lightning, wind and water damage.
 - g) Failure caused by reasons unpredictable by scientific technology standards at time of shipment from Mitsubishi.
 - Any other failure found not to be the responsibility of Mitsubishi or that admitted not to be so by the user.

2. Onerous repair term after discontinuation of production

- Mitsubishi shall accept onerous product repairs for seven (7) years after production of the product is discontinued.
 - Discontinuation of production shall be notified with Mitsubishi Technical Bulletins, etc.
- Product supply (including repair parts) is not available after production is discontinued.

3. Overseas service

Overseas, repairs shall be accepted by Mitsubishi's local overseas FA Center. Note that the repair conditions at each FA Center may differ.

4. Exclusion of loss in opportunity and secondary loss from warranty liability

Regardless of the gratis warranty term, Mitsubishi shall not be liable for compensation of damages caused by any cause found not to be the responsibility of Mitsubishi, loss in opportunity, lost profits incurred to the user or third person by failure of Mitsubishi products, special damages and secondary damages whether foreseeable or not, compensation for accidents, and compensation for damages to products other than Mitsubishi products, replacement by the user, maintenance of on-site equipment, start-up test run and other tasks.

5. Changes in product specifications

The specifications given in the catalogs, manuals or technical documents are subject to change without prior notice.

6. Product application

- 1) In using the Mitsubishi MELSEC programmable controller, the usage conditions shall be that the application will not lead to a major accident even if any problem or fault should occur in the programmable controller device, and that backup and fail-safe functions are systematically provided outside of the device for any problem or fault.
- 2) The Mitsubishi programmable controller has been designed and manufactured for applications in general industries, etc. Thus, applications in which the public could be affected such as in nuclear power plants and other power plants operated by respective power companies, and applications in which a special quality assurance system is required, such as for railway companies or public service purposes shall be excluded from the programmable controller applications.

In addition, applications in which human life or property that could be greatly affected, such as in aircraft, medical applications, incineration and fuel devices, manned transportation, equipment for recreation and amusement, and safety devices, shall also be excluded from the programmable controller range of applications.

However, in certain cases, some applications may be possible, providing the user consults their local Mitsubishi representative outlining the special requirements of the project, and providing that all parties concerned agree to the special circumstances, solely at the user's discretion.

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